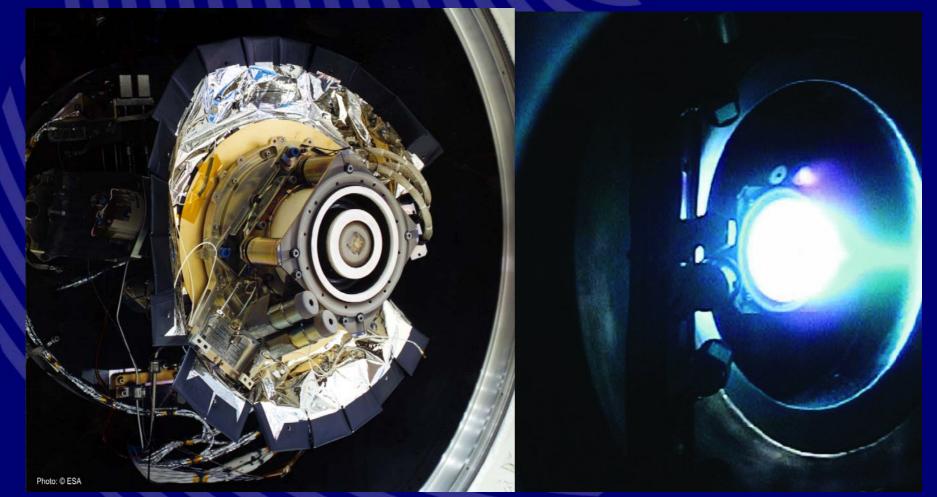
# SMART-1 Reserve slides



### Electric Primary Propulsion: 7 g thrust, 60 liters Xenon fuel to the Moon





### Europe to the Moon

#### United States (US)

General Dynamics: Hydrazine Propulsion System Ithaco Space Systems Inc: Reaction wheels L3 Communications: Electrical Ground Support Equipment TECSTAR: Solar Cells

#### Finland (FIN)

Finish Meteorological Institute: Space plasma electron and dust detection (SPEDE)

#### Sweden (S)

Swedish Space Corporation: Prime Contractor Omnisys Instruments AB: Power Control and Distribution Unit SAAB Ericeson Space AB: Flight Module Assembly Integration and Testing, Antennae, Remote Terminal Unit, Bectromognetic Compatibility, Thermal Subsystem

#### Denmark (DK)

Terme A/S: On-board Indepedent Software Validation DTU Technical University of Denmark: Star tracker

#### Germany (D)

Astrium GmbH: Deep space X/Ka-band (KaTE) MPI Aeronomies: Near Infrared Spectrometer (SIR)

#### Switzerland (CH)

APCO Technologies SA: Structure and Mechanical Ground Support Equipment Contraves Space AG: Electric propulsion mechanism CSEM: Asteroid-moon micro imager (AMIE)

#### Italy (I)

LABEN SpA: Electric Propulsion Diagnostic (EPDP) RSIS: Radio science investigation (RSIS)

#### United Kingdom (UK)

Rutherford Appleton Laboratory: Compact imaging X-ray spectrometer (D-CDS)

#### The Natharlands (NL)

Fokker Space: Solar Arrays TNO/TPD: Son acquisition sensors

#### Belgium (8)

Spacebel S.A: On-board software detailed design Alcatel ETCA SA: Electric propulsion power processing

#### France (F)

SAFT Division Defence et Espace: Batteries Snecmu Moteurs: Solar Array Mechanism, Electric Propulsion System (EPS) ATERMES: Electric propulsion pressure regulation Arianespace: Launcher (Ariane 5)

#### Spain (E)

Alcatel Espacio: S-band transponder CRISA: Battery management electronics

# The Launch

V162 lift-off on 27 September
 2003 at 23:14:39 UTC – The
 launch was perfect

SMART-1 separated at
23:56:03 into a GTO (656 x
35,881 km): perfect injection

 100 s later telemetry was received by Perth GS

Automatic activation
 sequence worked flawlessly





# **Technology Achievements**

Technology objectives fully achieved, through:

- Flight Earth-Moon powered by Solar Electric Primary Propulsion and making use of the lunar gravity assists and weak stability boundaries;
  - **Technology demonstration** 
    - advanced communications (Ka-band, Laser Link),
    - autonomy, novel navigation,
    - miniaturisation of instruments
    - spacecraft technologies (batteries, solar cells, computer, software)



# Spacecraft Technology

 New type of batteries, which allowed the spacecraft to withstand eclipses longer than expected,

•New types of solar cells, which resisted very well to the heavy bombardment in the radiation belts

•Compact onboard computer,

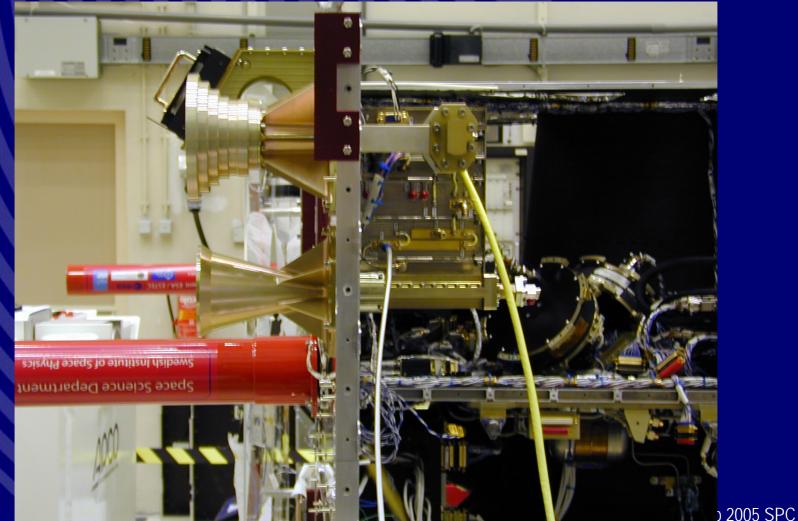
•Sophisticated SW which allowed to solve problems



# Cruise April-Nov 04 planning: a Smart musical score

sk Name	12 10		y '04	17 24	Jun '04		Jul '04	2 40 26	Aug '04		Sep '0		Oct '04		Nov '04
RESONANCE 1	12 19	20 0.	10	7 24	51 07	14 21 .	20 05 1.	2 19 26	02 09	16 23	30 05	15 20 .	04 1	10 25	01-08-1
RESONANCE 2		1								0.5	2				
RESONANCE 3														1	
AMIE Laser-link															
AMIE Earth imaging test													1		1
AMIE Earth tracking				<b>*</b>			8		8						
AMIE Star-Tracker alignment															
AMIE Earth staring															
AMIE cruise synoptic imaging of Earth (2/week)												1.0.0.0			
AMIE Geometric distortion with Pleiades															
AMIE Moon imaging near resonance															
AMIE Moon total eclipse imaging															28/10
AMIE OBAN (Earth and Moon imaging)															
DCIXS FOV calibration (target = SCO X-1)															
DCIXS (2 per week)					10.00.	8 <u>8</u> . 8.8	L 🛛 . 🖛 🖉 . 🖾	<b>0. 0. 0</b> . 0	.0.0.0.0	1. <b>0</b> . <b>0</b> . <b>0</b> .	00.00	. <b>.</b> . <b>.</b>	1, <b>0.0.0</b> .1	1.00.0	
KATE tests Villafranca 4															
KATE-RSIS EP monitoring with DSS13											2				
1 week for KATE tests with Villafranca 4								<b>.</b>					<b>.</b>	<mark>.</mark>	
SPEDE-EPDP magnetopause measurement											<b></b>	<b>II</b>	<b></b>	<b>I</b>	
EPDP SC calibration (1 acquisition per week)									II	<b>I.I</b>		II.I		<b>.</b>	1
XSM (1 per orbit)															
AMIE-SIR alignment			⊠												
SIR Jupiter observation						E	2					a	J		
SIR Earth scan and spectral calibrations									10000000	8			8		

# Communication Technology: Ka-band



# KaTE ground station

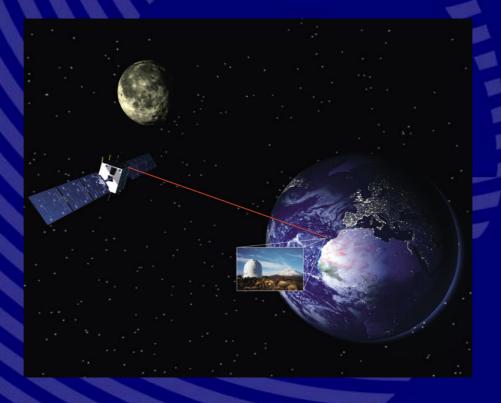




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# Laser Link experiment



Cesa\_\_\_\_\_

# Laser Link

### **Demonstration for future deep space optical communication**

Sun light

OGS

 Determination of an accurate alignment procedure
 Characterization of laser beam propagation through atmosphere & space for various link distances and elevations

Reflected Sun light

SMART-1

Coudé FOV = 8 arcmin

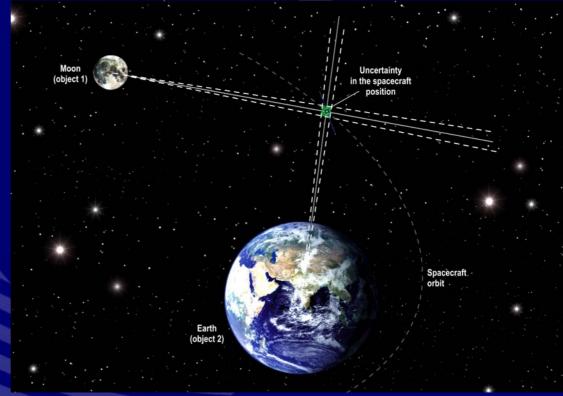
LASER BEAM DIVERGENCE = 2 to 6 arcsec



OBAN

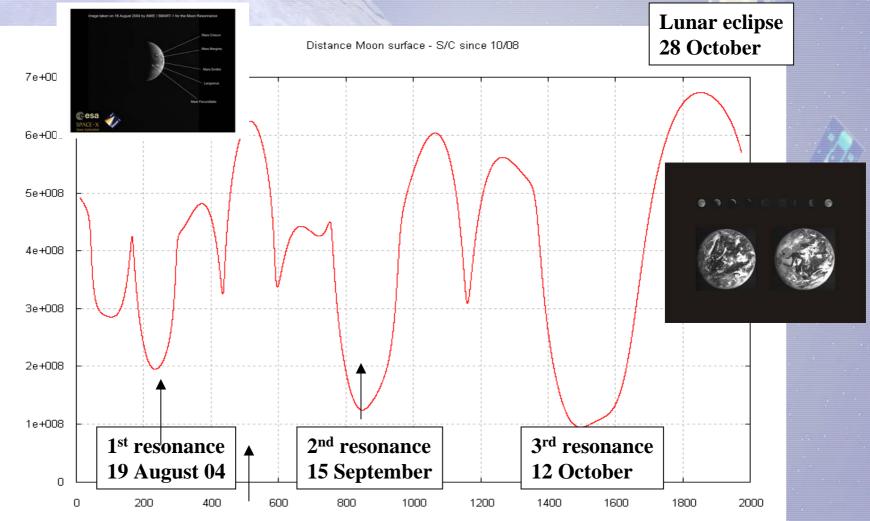
AMIE camera and the Star Tracker are used to make images of solar system objects

 By triangulation determine the position and the velocity of the spacecraft





### From resonances to eclipses SMART-1 Distance to the Moon



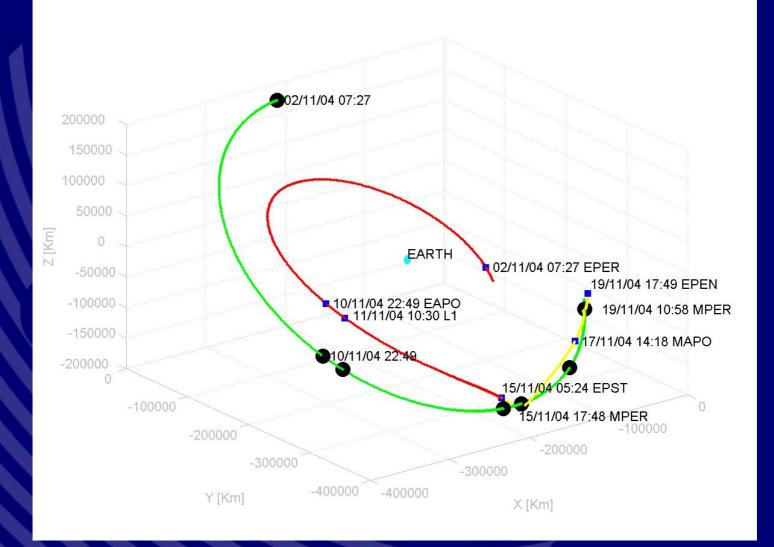
time (h)

SCIENCE

216.18, 1.86667e+008

Distance (km)

### Final approach to first lunar orbit to the Moon



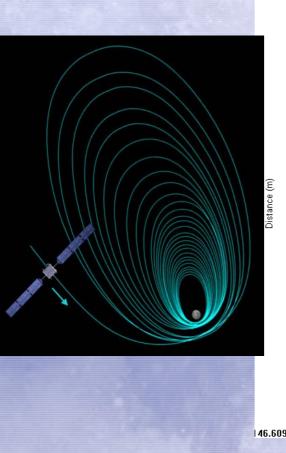
Cesa\_\_\_\_

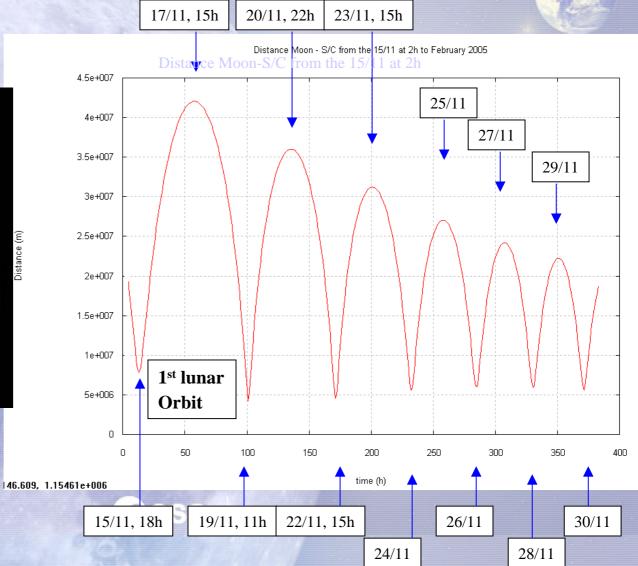
### SMART-1



### Spiralling down closer to the Moon,

### towards science orbit 300-3000 km after 15 January 05

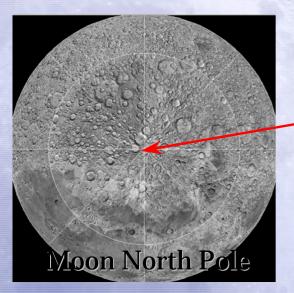


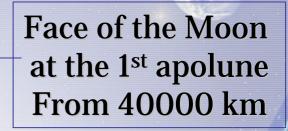


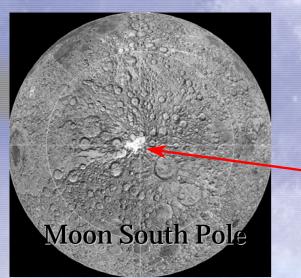
### SMART-1

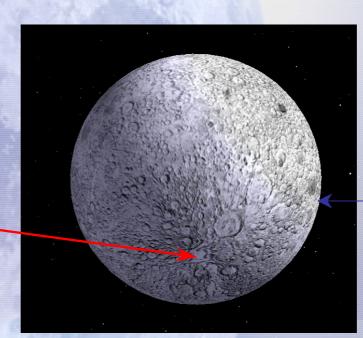


### **1st Perilune-Apolune around the Moon**









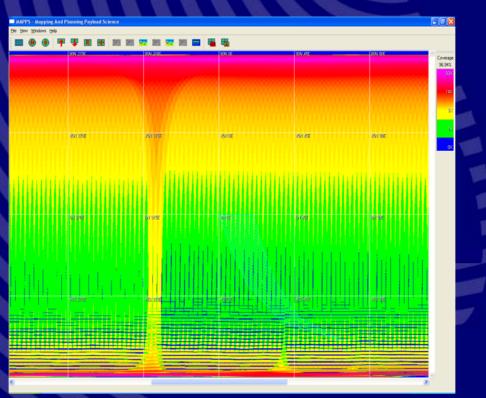
Face of the Moon at the 1st perilune From 5000 km



ESA-SPACE-X 01Nov 00.00.32z



## Full-frame global mapping, 50% overlap low res survey from 1000- 4500 km



•"Simple and systematic" mode of operation – default nadir pointing and repetitive commanding



## **SMART-1 Science/Exploration Opportunity**

- INSTRUMENTS READY FOR LUNAR TASKS
- 1<sup>st</sup> X-ray global mapping for Mg, AI, Si at 50 km resolution
- 1<sup>st</sup> infrared spectral mineralogy mapping 0.9- 2.5 microns
- Local multi-band mapping at resolution 40 m from 300 km
- Polar areas illumination and resource mapping
- Stereo mapping for Digital Elevation Models



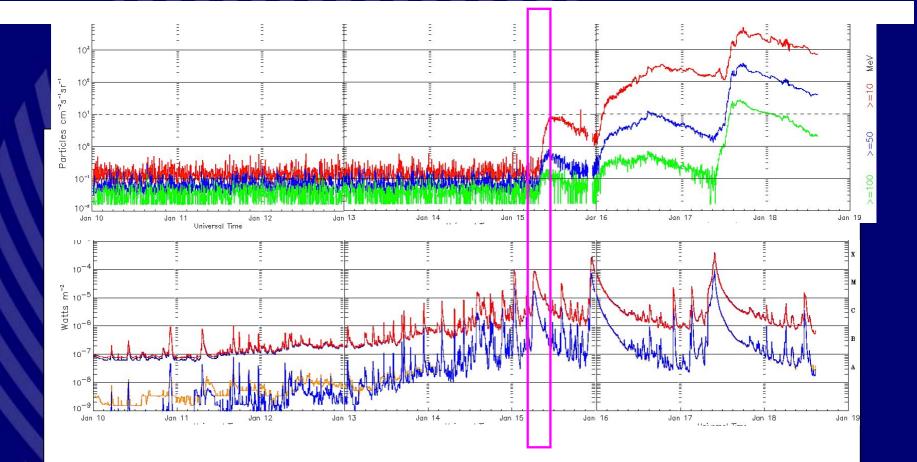
	10
Clementine Filter B (750 nm)	
	a.
Clementine Color Ratio	
The second second	
	Ling .
Perspective view	





Community support: operation, PDS archive, data analysis and science exploitation Extension to 2006, and joint international investigations





This is proton (top) and X-ray (bottom) data from the GOES space weather monitor. Early on January 15<sup>th</sup> there is an M9 X-ray flarer.<sup>C</sup>.

# Assumption for science payload operations:

- Standard mode: payload operations conducted over illuminated side of the Moon pole-to-pole:
- priority 1 from south pole to 2000 km distance (with nadir or near nadir pointing)
- priority 2 for part 2000-3000 km
- priority 3 operations on dark side (pending spacecraft platform operations and data download)
- Off nadir pointing and targeted observations during extension phase
- STWT & Project scientist overall responsibility for science operations
  - long term science planning (with STWT and RSSD support staff)
    - mid-term and short term operations (with PIs, STOC and ESOC staff)
    - data archiving (with PIs and RSSD Planetary science archive staff)



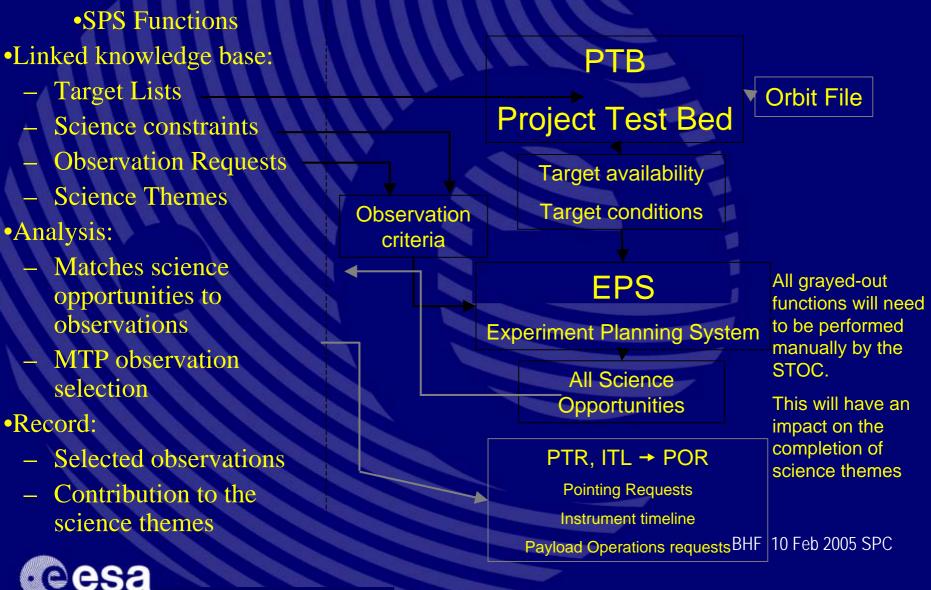
# 5MART-1 Science Management Plan SPC nov 99

- The ESA Project Scientist will act as the Chairman of the SMART-1 Payload Working Team (SPWT), and as such coordinate its activities.
- The ESA Project Scientist will assume responsibility for management of the SMART-1 Project at a suitable time after launch.

 The SMART-1 data rights will follow the established ESA rules (ESA/C(89)93). Therefore all scientific data obtained during the full mission duration will remain proprietary of the Investigator teams for a period of up to 6 months after they have been received from ESA.



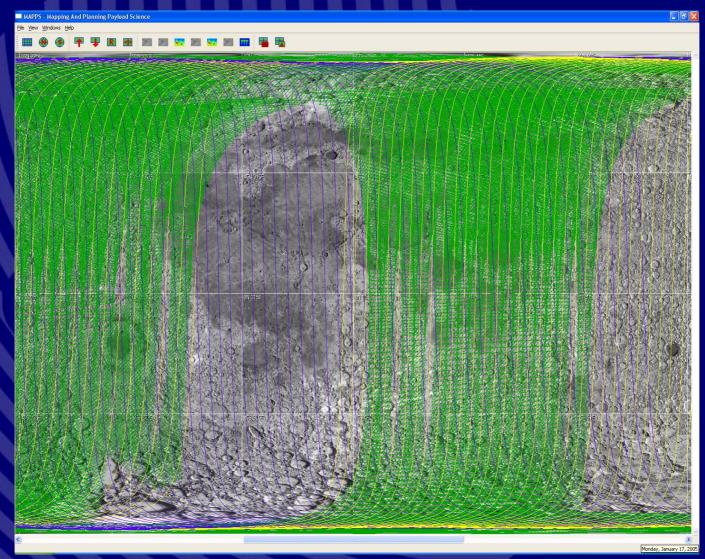
# Science Planning Software – Present status



# • Constraints: nominal uplink every 4 days = 8000

- - Max commands/APID = 4096., POR Payload Operation Request= 9999
- Executed Operations: New Year: colour with 50% overlap at 1000-5000 km orbit
  - 137 images\*9 commands\*3 orbits ~ 4000/day
    - solution 1, use 4 APIDs
    - solution 2, uplink every day
    - solution 3, reduce # of commands/image (proposal to reduce to 5 tbc by AMIE)
    - solution 4, reduce number of images to 35! •
- Consolidated operations: Jan 2005: colour imaging
  - 122 images\*5 commands\*3 orbits =  $\sim 2000/day$ 
    - solution 1, use 2 APIDs •
    - solution 2, uplink every 2 days •
    - solution 3, reduce # of commands/image
    - solution 4, reduce number of images! •
- Future Operations: Science phase: 20% overlap to avoid gaps due to s/c rotation
  - 150 images\*5 commands\*5 orbits ~ 2750/day
    - solution 1, use 3 APIDs! •
    - solution 2, uplink every day 0
    - solution 3, reduce # of commands/image to 1 macro-command •
    - solution 4, compromise: reduce # of commands/image to 2, uplink every 2 days Feb 2005 SPC lacksquare
    - solution 5, reduce number of images to < 40

# **January Low resolution Coverage**



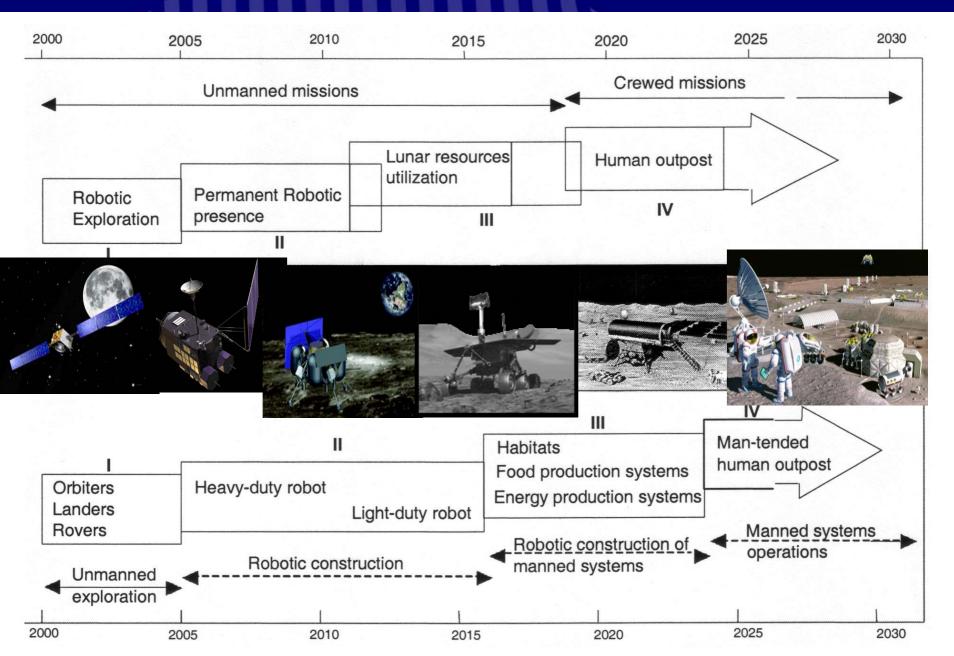


# Case for 1 year extension

- to extend the global coverage for AMIE, SIR, DCIXS
- due to 1 mrad FOV and telemetry limitations, it is expected that only a few percents of the surface will be covered by the SIR spectrometer after 6 months
- due to telemetry limitations the extension permits to augment coverage by the AMIE camera at high res colour mode
- Only 2 over 6 months give good illumination conditions for IR spectrometry, X-ray sensitivity and quantitative colour radiometry
- increases the probability of solar flares events (in rising solar activity) for very sensitive D-CIXS scans providing high res maps Fe
- to perform dedicated programmes to prepare future international lunar missions
  - mapping potential landing sites for future missions (including South pole Aitken sample return)
  - Measurements in coordination and preparation for observations with Lunar A cameras and Selene, Chandrayaan-1, Chang'E and LRO, seasonal illumination maps at high resolution)



### ILEWG phased approach for lunar exploration



### Roadmap for international lunar exploration

### 2014 International Robotic village

- Robotic outposts: geology, water ice, life sciences,
- Advanced landers/rovers from international partners
- In Situ Resource Utilisation (power, minerals, H, O, He3)
- Life support systems, deploying larger infrastructures
- Autonomous & intelligent robots prepare for humans
- 2017 Man tended missions
- 2024 Permanent Lunar base
  - Living off the land on another planet
- Moon as SMART testbed for technologies

  human/robot optimised operations,
  step to Mars and solar system exploration

Science, technology, exploration, societal synergies
Aurora/exploration, Cosmic Vision 2015-2025
Develop Europe as strong international space partner

Inspiring an innovative and competitive Europe







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