Mission and Spacecraft Design Concepts for the Euclid Satellite


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1. Design drivers
2. Configuration rationale
3. Main trade-offs
4. PLM design
5. Instrument design
6. Survey strategy
**Design Drivers**

**Multiple DE probes**
- One telescope feeding 3 instruments

**Survey speed**
- Large Field of View (0.5 deg²) / Optimised sky survey strategy / Fast attitude slews

**Survey depth and signal to noise ratios**
- Well baffled design / Cold telescope for low background / On board data processing for noise limitation / Cryo optics and detectors

**Size reconstruction and stability of the Point Spread Function**
- High image quality / Large data rates / Payload in the AOCS loop
- Permanently shaded, temperature-controlled telescope (thermoelastic stability)

**M-mission cost ceiling and target launch date**
- Passive cooling (→ L2) / Telescope aperture limited to 1.2 m / Limited number of NIR detectors / Any new technology demonstrated by test by 2011.
Satellite configuration rationale

**Sunshield**
- Stable, controlled thermal environment with little variation between hot and cold cases

**Baffle**
- Straylight suppression (pending future analysis)
- Contamination protection (baffle cover, not shown in drawings)

**Pre-integrated instruments**
- Parallel developments to relax schedule constraints

**PLM mechanical-thermal concept**
- Double truss for low deformation, ease of AIT
- Separate, controlled thermal environments

**Herschel-like SVM**
- Design and development heritage
- Wide room for warm payload electronics
Design trade-offs overview

Experiment policy trades (ESA)
- Step-and-stare vs. continuous scan
- Instrument-level vs. satellite-level dithering
- Multi-slit vs. slitless spectroscopy

Telescope accommodation trades
- Straylight & stray heat protection: Baffle-and-sunshield solution preferred
- Low vs. ambient telescope temperature: 240 K, driven by NIR background

Experiment accommodation trades
- Highly modular accommodation: each instrument can be specified, developed, tested and integrated as a self standing unit.
- Decentralized instrument data handing architecture: instrument-own ICU (control and drive) / DPU (data processing and compression)

Attitude measurement and control trades
- Fine Guidance Sensor co-located with VIS focal plane and sharing VIS optics
- GAIA type micro thrusters vs. magnetic-bearing reaction wheels: driven by mass budget
Modular, Ultra Stable and Stiff Structural concept

1.2m Zerodur M1 on kinematic mounts

Very stable & stiff Si3N4 truss structure

Highly stable & strong CFRP bench box

VIS+ NIP M3 on a CFRP truss

VIS FPA+rad

NIP FPA + rad

Lower cavity

NIS FPA + radiator

The 3 focal planes are accommodated on the cold side of the satellite
Materials selection

- Mirrors
  - M1 specification
    - Residual WFE (PTF)(1g-0g ⊕ polishing ⊕ 300K- op T\text{ure}) <20nm RMS
    - Focus stab : R= 4.6m ; ΔR<10µm (2390s)

  ➔ Mirrors thermal stability needs

  ➔ Performances already demonstrated on Zerodur equivalent mirror
  - M1-M2 structure thermal stability needs 3 µm

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<th>170 K</th>
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Over a large temperature range (ambient to 170 K), Zerodur mirrors and Si3N4 structural parts provide the highest M1M2 stability, and the most affordable demand on thermal control.
The optical design was received from ESA and adapted by the TAS team to improve its accommodability.

**Rationale**
- improve accommodation of elements
- reduce volume (height) and mass of payload and S/C structure
- facilitate assembly and integration of instruments (avoid oblique mechanical I/F)

**Solutions**
- increased distance between M1 and NIS folding mirror (accommodation issue);
- VIS and NIP put on the same XY plane to reduce satellite height (volume, mass issue);
- all FPAs placed on the same side to make thermal design feasible (thermal design aspects);
- NIS rotated in the XY plane by 90° to remove conflict with VIS/NIP components and rays;
- dichroic tilted to improve VIS accommodation.

The new design is completely compliant with the requirements.
Equipped focal plane preliminary design

Already qualified large CeSic focal plane

CeSic FPA equipped with 36 + 4 detectors

kinematic mounts

CeSic FPA radiator

x (36+4)

CeSic focal plane

VIS Design
NIP / NIS Units Implementation

- Lens mounting
- FPA
- NIP
- M3 mirror
- Lens / Grism Unit
- Fold mirror

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- Large on board data processing load
- Independent instruments from different consortia
- Individual development and test requirements
  → Decentralized architecture

NIP electrical block diagram
NIR Photometric Model

Detailed Photometric Model

- Detector sampling,
- NIR Instrument BG
- Dithering

Observation Time

- WES
- Deep Survey

Operating Temp

- Telescope (240 K)
- Instrument (188 K)
- Components (188 K)

Instrument Design

- Lyot-stop
- Cut-off filter
- Baffle design

Data Handling

- Up-the-ramp sampling
- Data budget (339 MFLOP)
- Data processing

SNR vs. t, Dtel=1.2m, M(AB) = 24, CDS Read noise 12, J Band, if = 12 s

Total Integration Time [s]

SNR

IR Background [e/s/pix] vs Instrument Temp.

Solid angle of instrument radiation seen by the central pixel

Lyot Stop and Instrument Temperature [K]
Observation procedure

Dithering by s/c, 4 dithers, 3 NIP bands

- Filter wheel turn does not disturb observations → requirement
- Shutter operation incompatible with continued observations
- 4 x 500 s + short (100s) NIS imaging phase

Total cycle of about 2400s
- 36 x 0.48 deg² fields/day
**Basic Strategy**

- Scan strip by rotating S/C about X-axis (nominally the sun line)
- After the S/C has moved 1° on its orbit around the Sun, rotate S/C about its Z-axis to restore SAA, and start new strip
- Strips lie on great circles perpendicular to the S/C-Sun direction; movement of the S/C around the Sun changes the longitude of the great circle scanned

**Modified strategy**

- Flexible time: time when basic strategy would produce redundant observations (ecliptic poles & equinoxes)
- In flexible time, use 30-deg SAA d.o.f. to cover blank spots
- Strategy succeeds to cover extragalactic caps in 4 yr
- However, longer field dwell time has reduced pass redundancy at high ecliptic latitudes (important for Deep Survey)