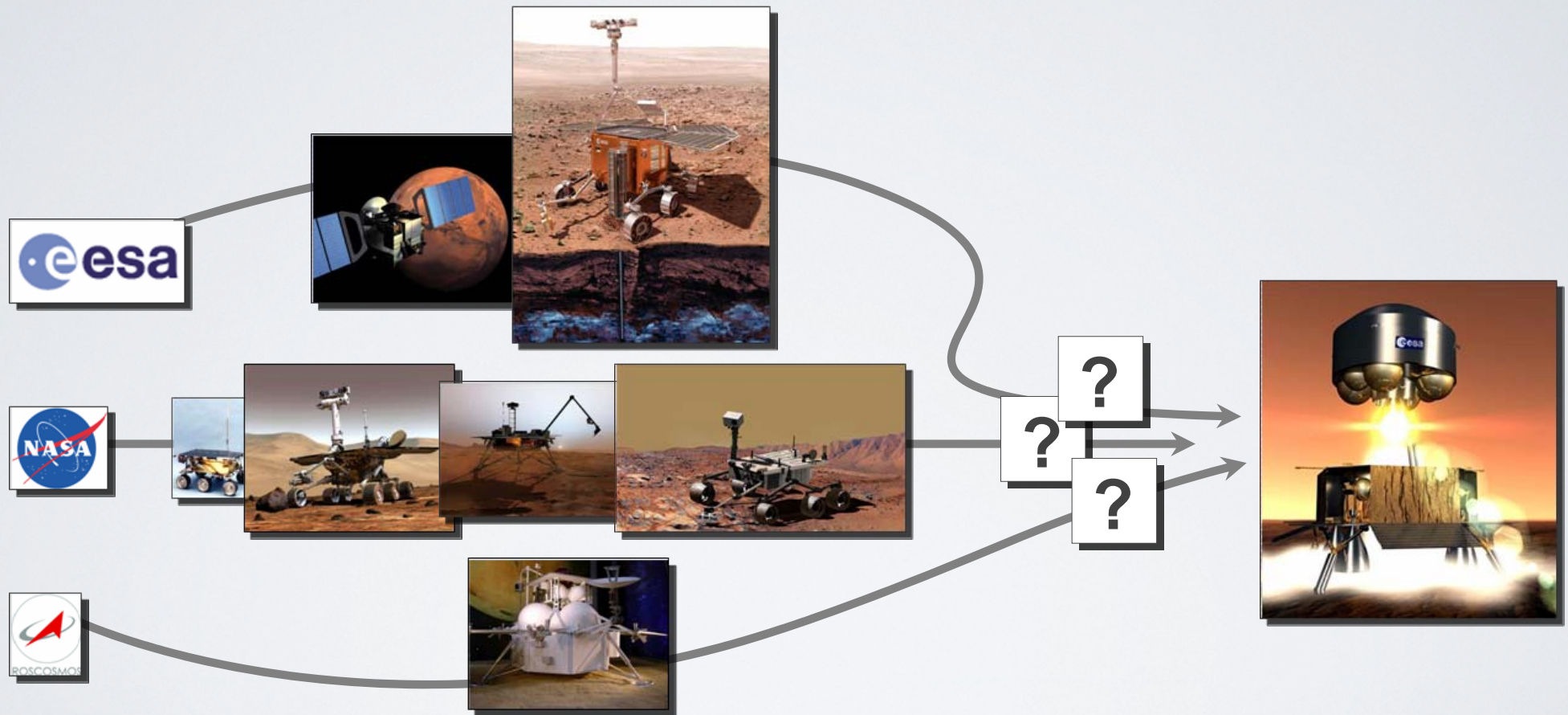


# The ESA/NASA ExoMars Programme

- Recognising that a Mars Sample Return (MSR) mission is very challenging, and that its undertaking will likely exceed the financial capabilities of any one agency,  
one agency,



- ESA and NASA have agreed to embark on a joint Mars robotic exploration programme:
- Y Initially, seek agreement on mission configurations for 2016, 2018, and 2020 opportunities;
- Y ExoMars becomes a key element of the 2016 and 2018 scenario;
- Y ExoMars spreads its objectives over two opportunities.



## 2016

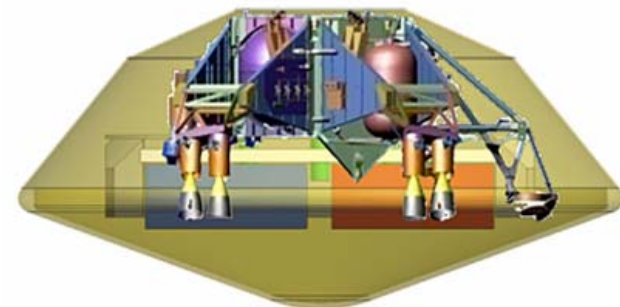
### ESA-led mission

Launcher: NASA - Atlas V 421  
 Orbiter: ESA  
 Payload: ESA-NASA  
 Lander: ESA

## 2018

### NASA-led mission

Launcher: NASA - Atlas V 531  
 Cruise & EDL: NASA  
 Rover 1: ESA  
 Rover 2: NASA





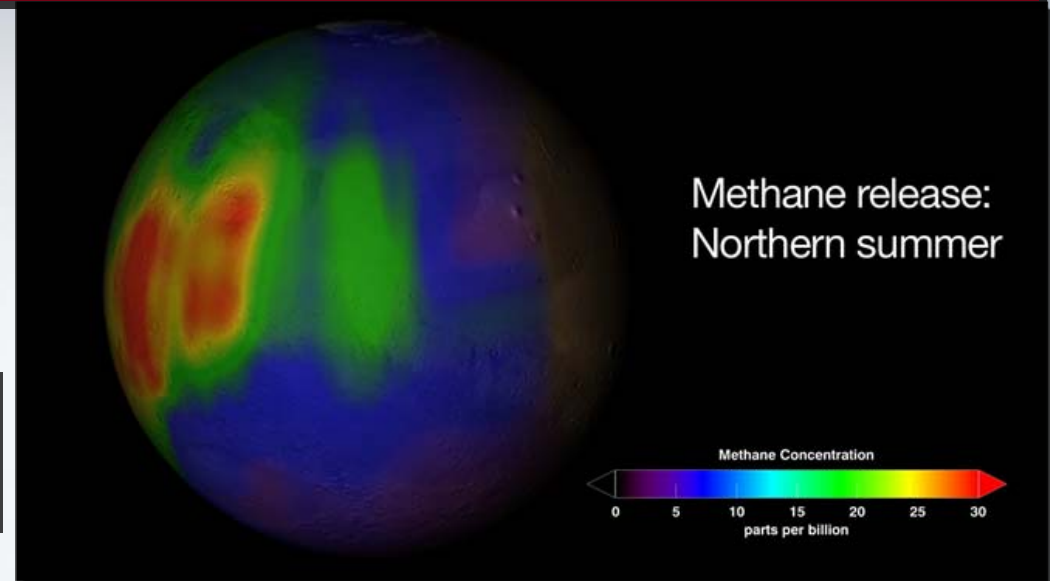
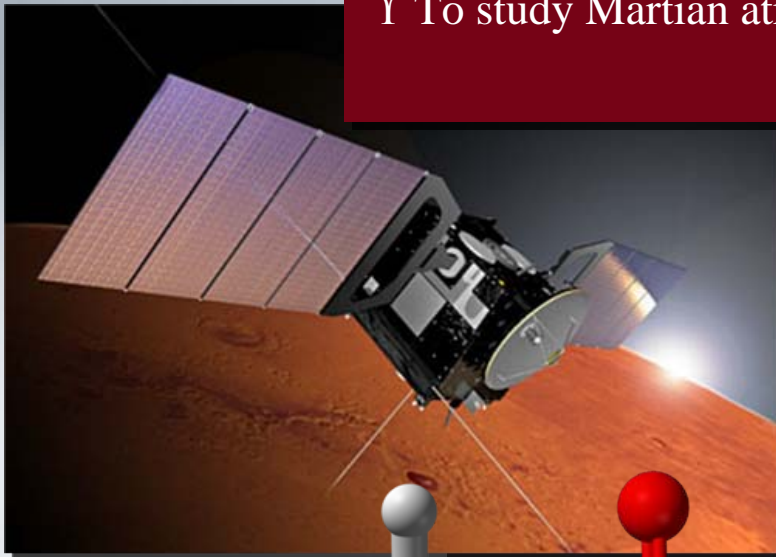
2016

## TECHNOLOGY OBJECTIVES

- Y Provide data relay services to landed missions until 2022;
- Y Entry, Descent, and Landing (EDL) of a payload on the surface of Mars

## SCIENTIFIC OBJECTIVE

- Y To study Martian atmospheric trace gases and their sources.



#	Acronym	Description	View Modes	Observation Modes	
1	SFTIR	Solar Fourier Transform IR Spectrometer: <b>Broad survey</b> of trace gases with high precision	Solar Occultation only; passive radiative cooler	2 Solar Occultations per orbit (~24/day); processing interferograms throughout orbit	
1	SLNIR	Solar-Nadir IR Mapper: Detection and mapping of <b>specific</b> trace gases	Solar occultation; nadir and limb viewing; heat sink required (assumed to be provided by s/c)	2 solar occultations + dayside nadir/limb (60 min) on each orbit	
2	Sub-mm	Sub-mm Spectrometer profiler/mapper <b>Atmospheric temperature &amp; winds</b> plus <b>H2O and specific</b> trace gases	Nadir and limb, including away from velocity vector	Continuous operations switching between nadir, space, different limb; observe both sides of ground track	
2	TIR	Thermal IR profiler/mapper spectrometer or radiometer for atmospheric <b>temperature and dust</b> , plus <b>H2O and some</b> trace gases	Nadir and limb views, including away from velocity vector	Continuous operations switching between nadir, space, different limb; observe both sides of ground track	
2	WAC	Wide Angle Camera imaging <b>atmospheric phenomena</b> for discriminating between surface, dust clouds, & ice clouds	push-frame operation with .GE. 2 color bands; requires alignment with ground track motion	Cross-track (nearly orthogonal to velocity vector) horizon-to-horizon	
3	HRCSC	High Resolution Color Stereo Camera: <b>Surface imaging</b>	~1 m/pixel ground sampling (at nadir) with TDI; fore/nadir/aft views	Designated targets of opportunity; requires alignment with ground track motion (mitigation needed)	

2018

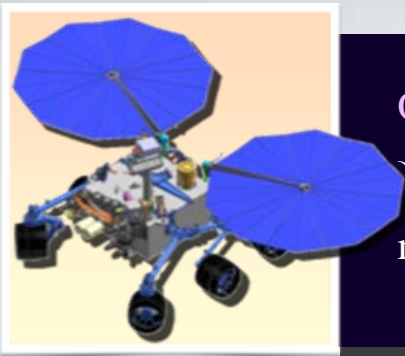


## TECHNOLOGY OBJECTIVES

- Y Surface mobility with a rover (having several kilometres range);
- Y Access to the subsurface to acquire samples (with a drill, down to 2-m depth);
- Y Sample acquisition, preparation, distribution, and analysis.

## SCIENTIFIC OBJECTIVES

- Y To search for signs of past and present life on Mars;
- Y To characterise the water/subsurface environment as a function of depth in the shallow in the shallow subsurface.



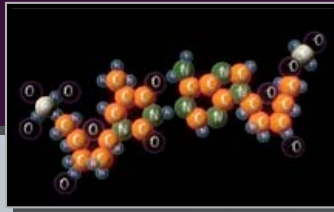
## OBJECTIVE

- Y To identify, acquire, document, and cache “outstanding” samples in a manner suitable manner suitable for collection by a future Mars Sample Return mission.

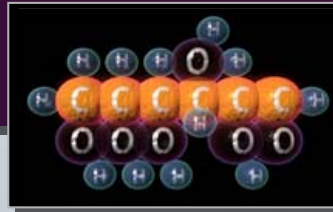
- PRESENT LIFE:** Biological markers, such as:



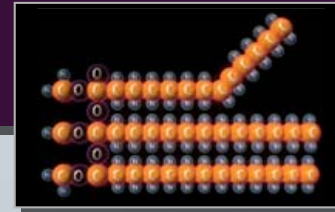
Amino acids



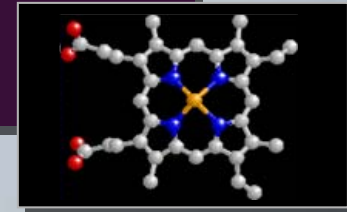
Nucleobases



Sugars



Phospholipids

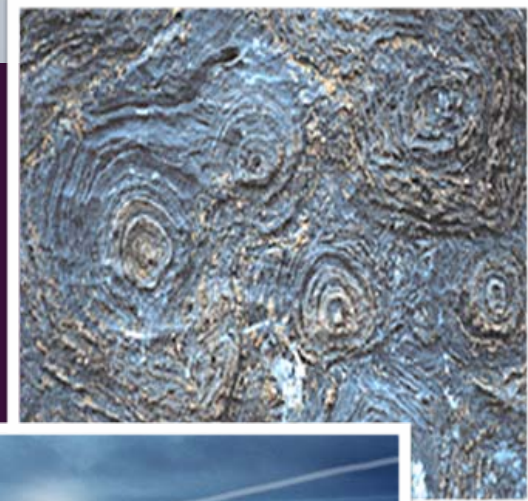


Pigments

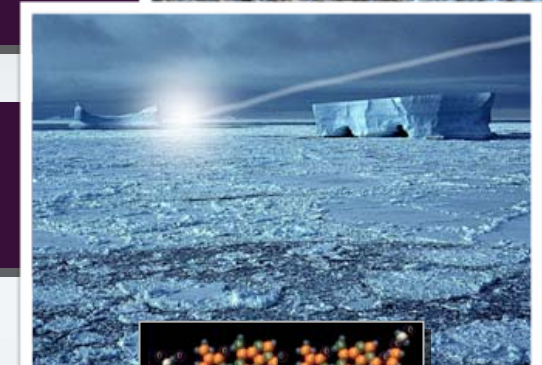
...

- PAST LIFE:** Organic residues of biological origin;  
(chemical, chiral, spectroscopic, and isotopic info)

Images of fossil organisms and their structures;  
(morphological evidence)



- DELIVERED ORGANICS:** by meteoritic and cometary infall



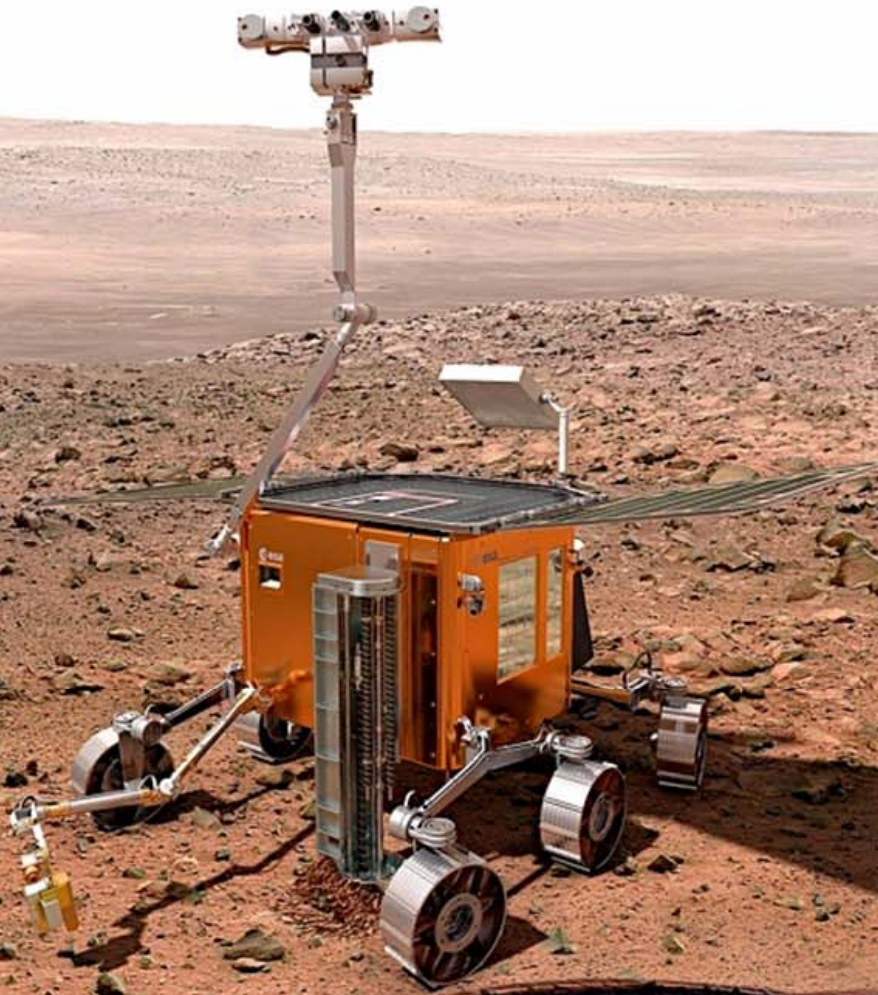
# The EDLS Demonstrator

A horizontal banner with a blue background on the left showing several small, translucent spheres. On the right, a larger, detailed image of the planet Mars is shown. The word "EXO MARS" is written in white capital letters across the top of the banner, with the "O" in "EXO" positioned over the Mars image.

E X O M A R S

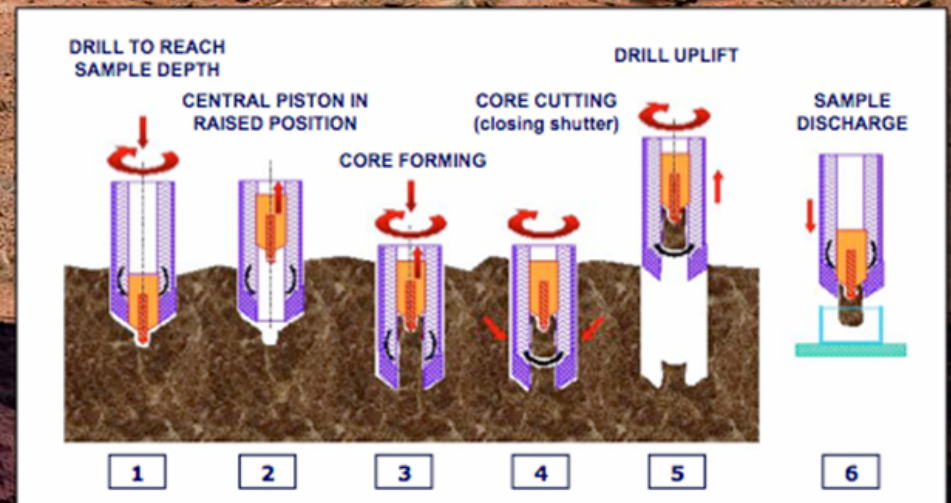
- **Maximum Mass at launch 600Kg**
- **Semi-soft (almost soft) lander with liquid retro-propulsion**
- **Landing gears (TBD) crushable material, vented airbags, legs**
- **Minimum Payload operated on primary battery (5-7 sol lifetime)**
- **Mass less than 5Kg and no deployment mechanisms**
- **Science Goals: mostly environmental assessment**





2-m depth

Nominal mission:	180 sols
Nominal science:	6 Experiment Cycles + 2 Vertical Surveys
EC length:	16 – 18 sols
Rover mass:	300 kg
Mobility range:	Several km



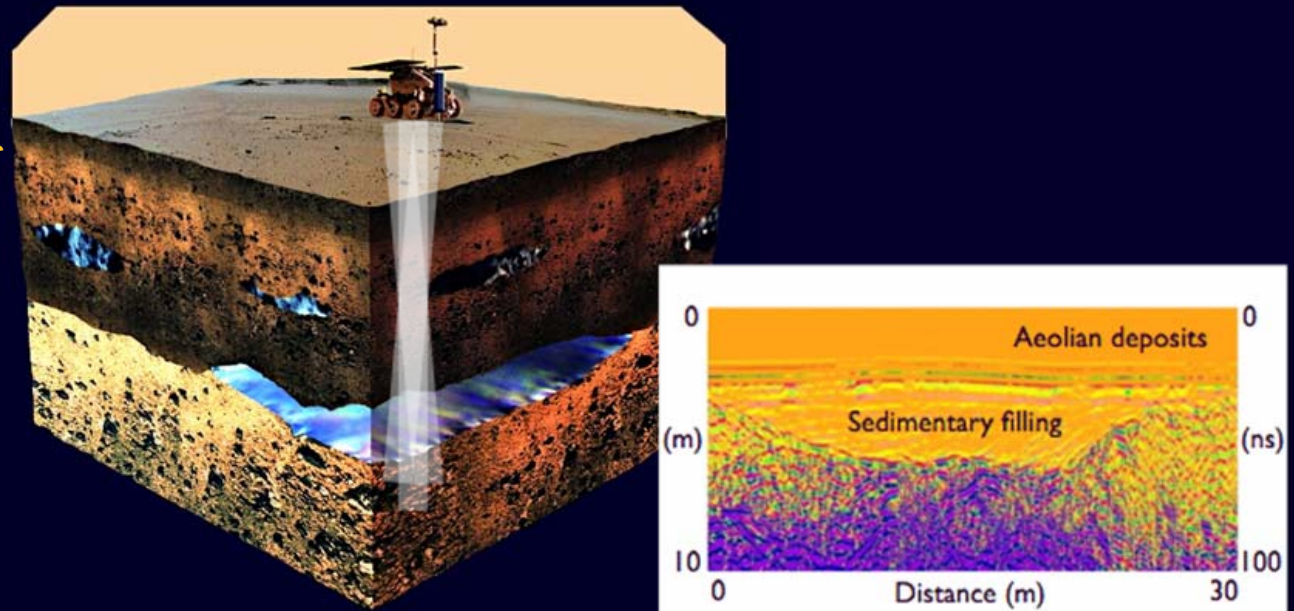


**AT PANORAMIC SCALE:**  
context

To establish the geological



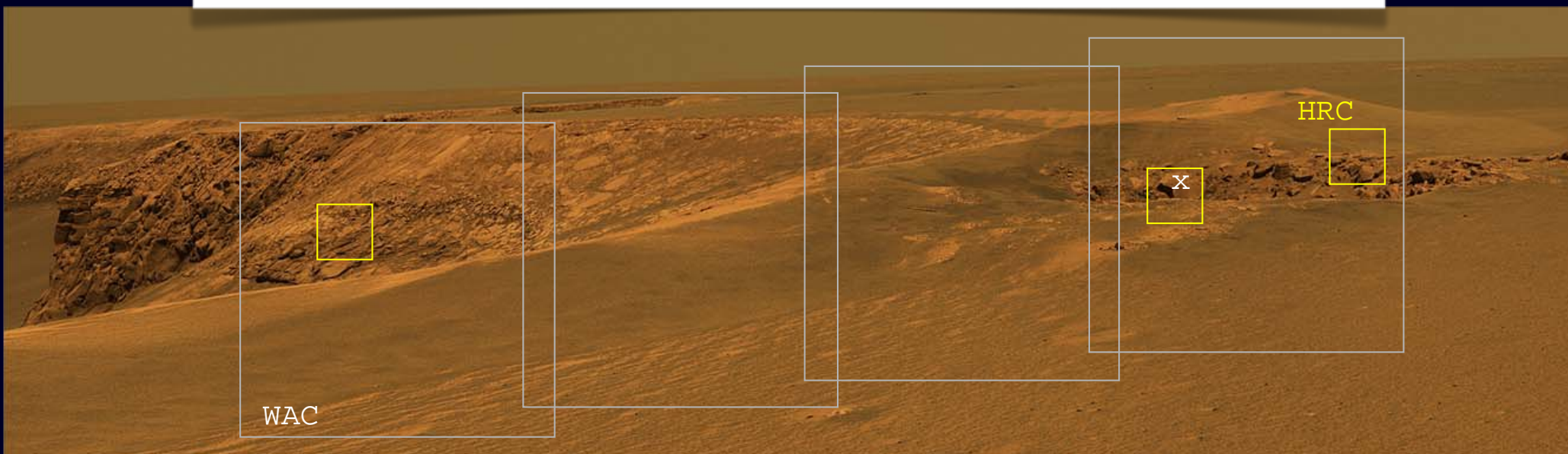
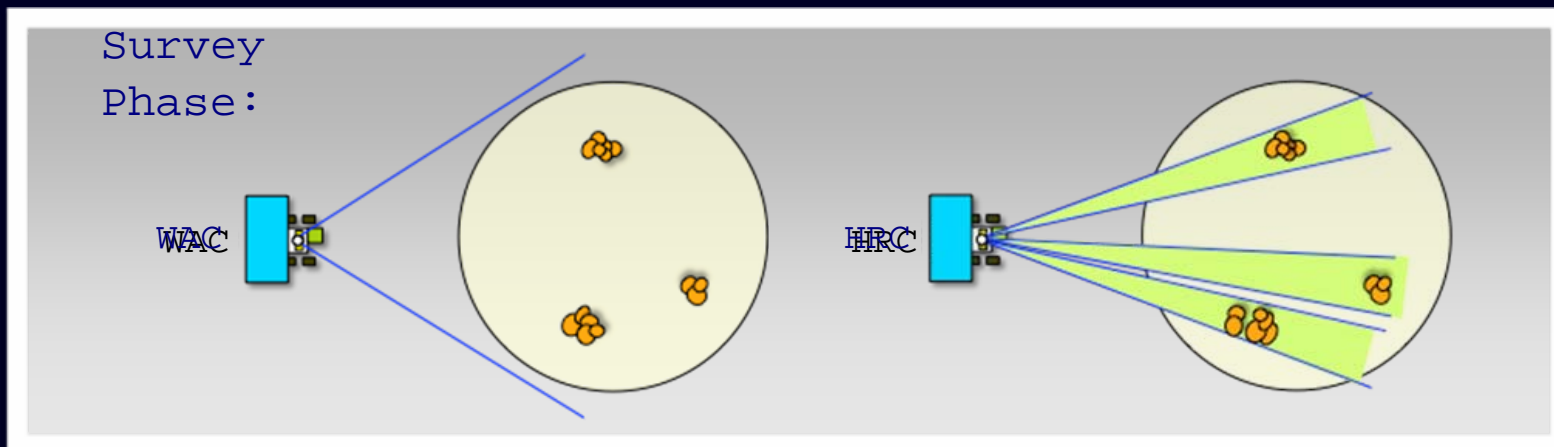
**Ground Penetrating Radar**



Heggy et al. 2007

**AT PANORAMIC SCALE:**  
context

To establish the geological





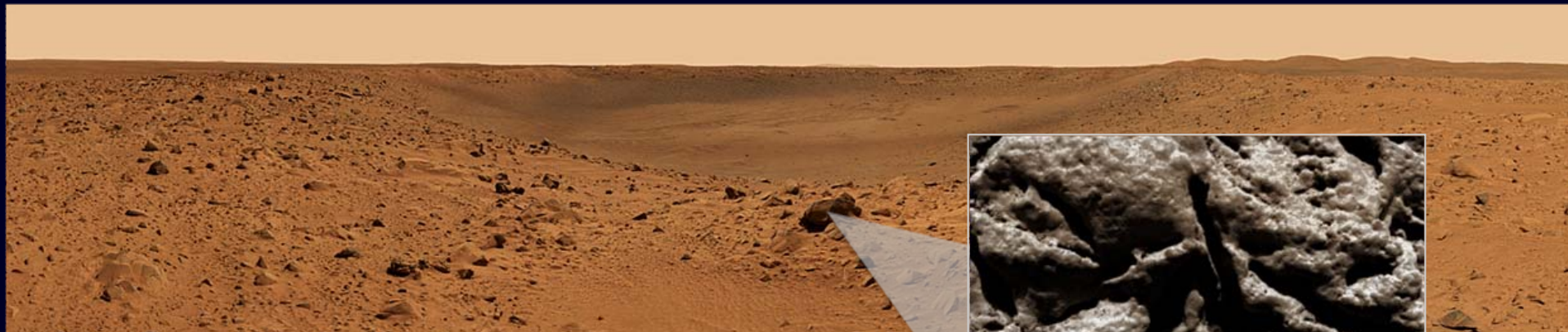
## AT ROCK SCALE:

water

To ascertain the past presence of

For a more detailed morphological

examination



High-Resolution

Camera

Close-Up Imager



Next step: **ANALYSIS**

Use the drill to collect  
a sample

From an outcrop

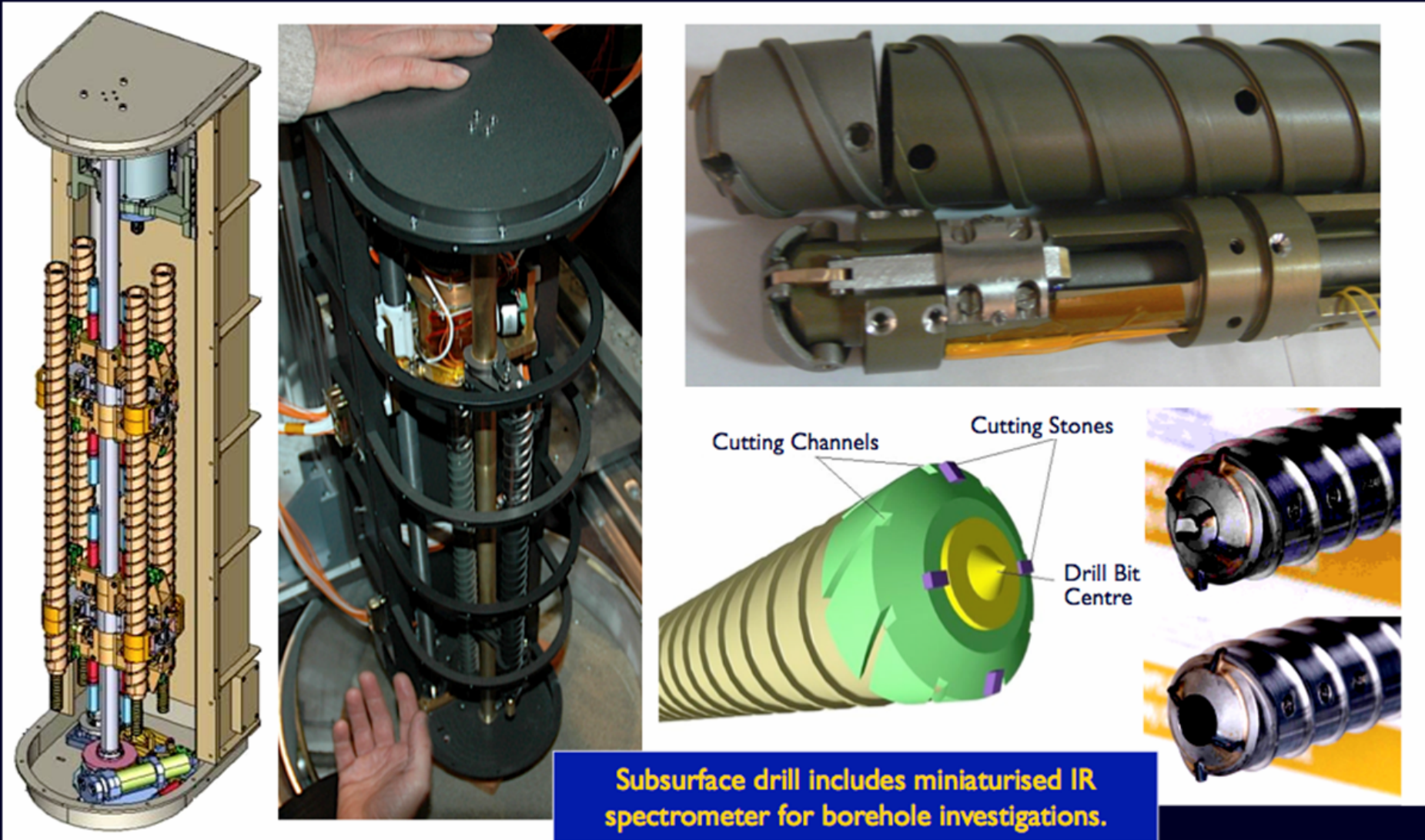
From the

subsurface

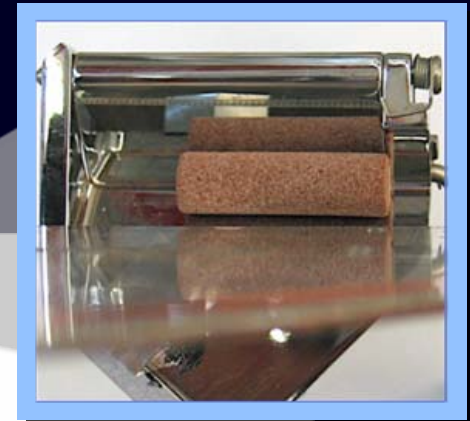
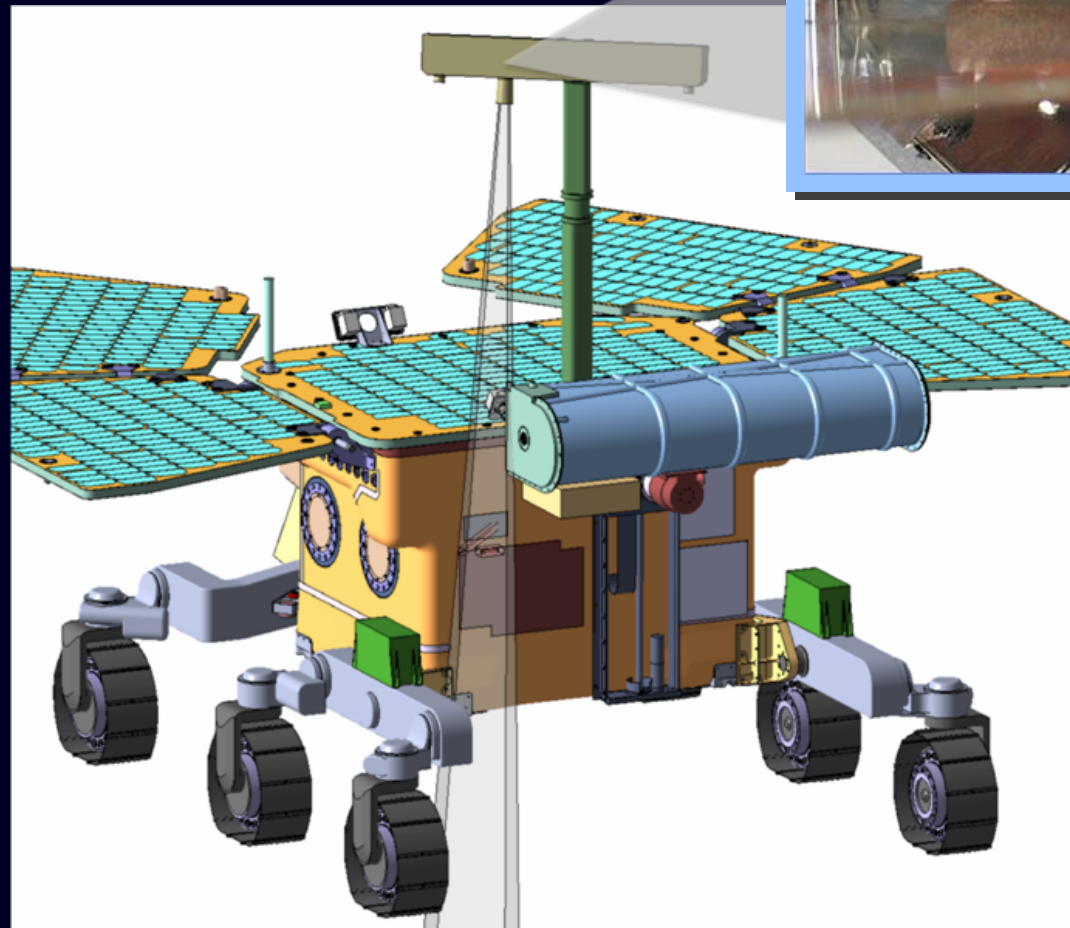
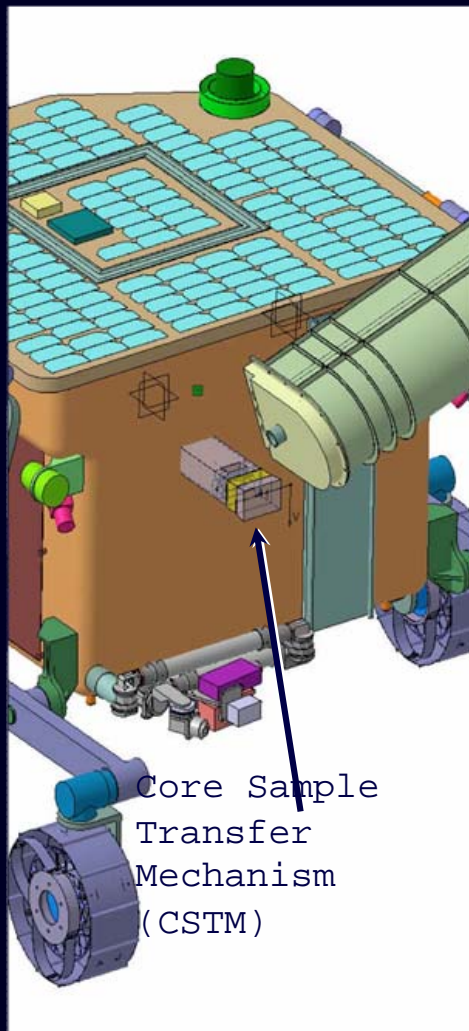


**OBTAIN SAMPLES FOR ANALYSIS:**

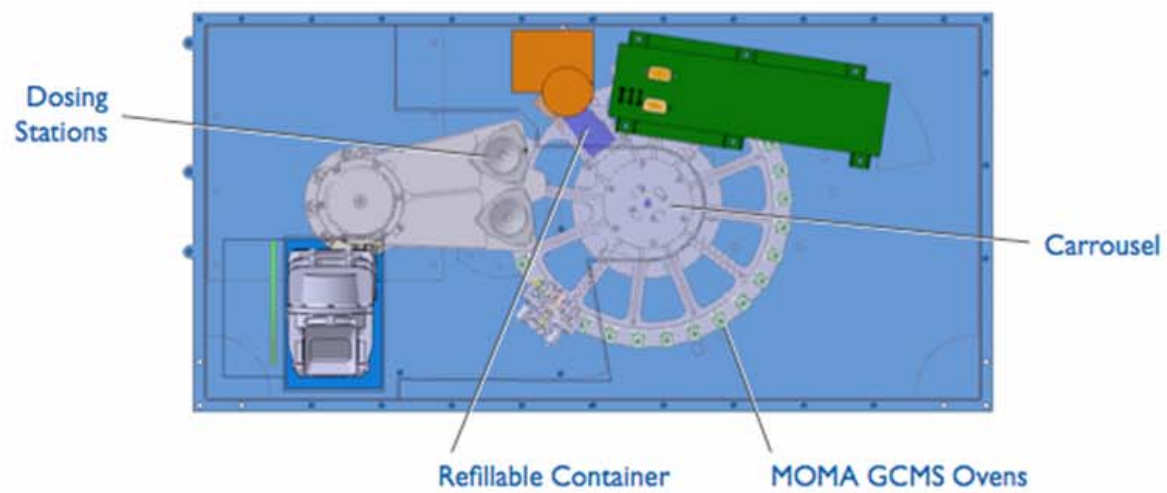
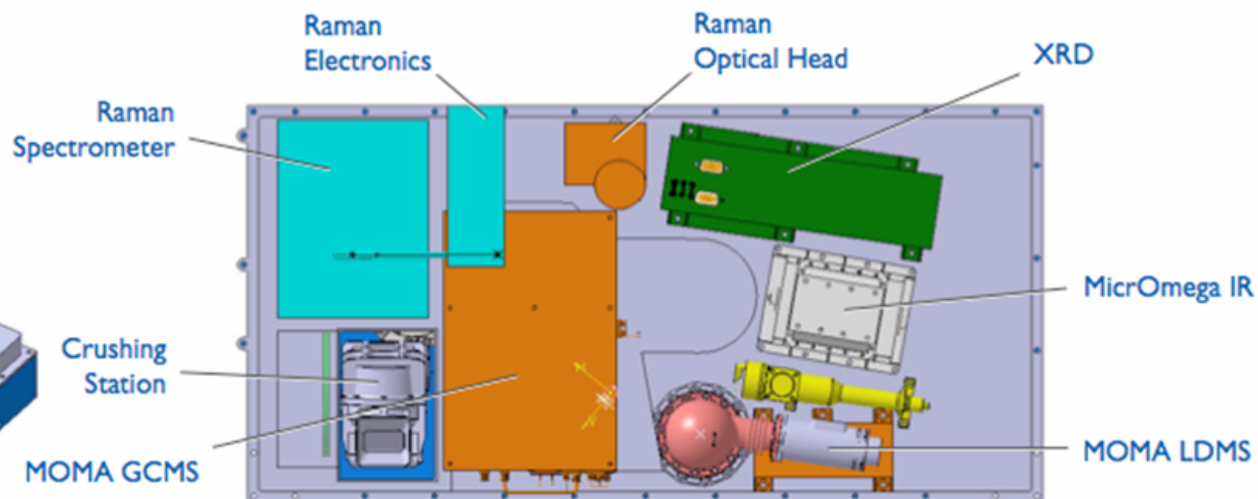
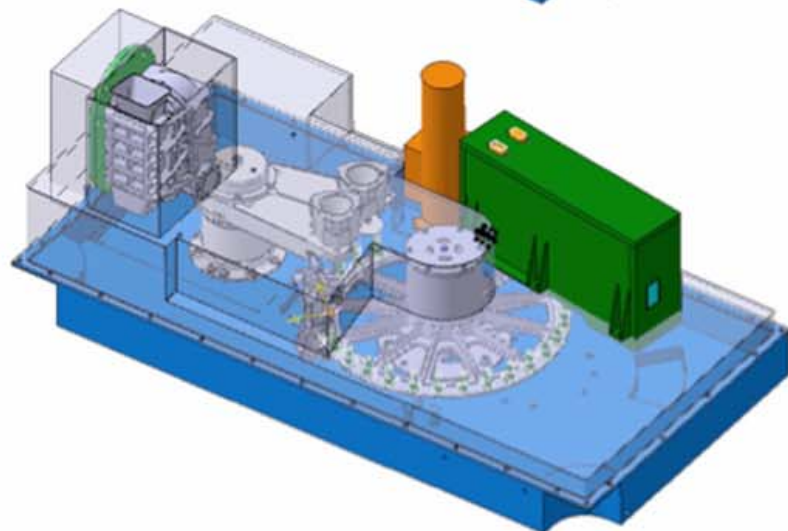
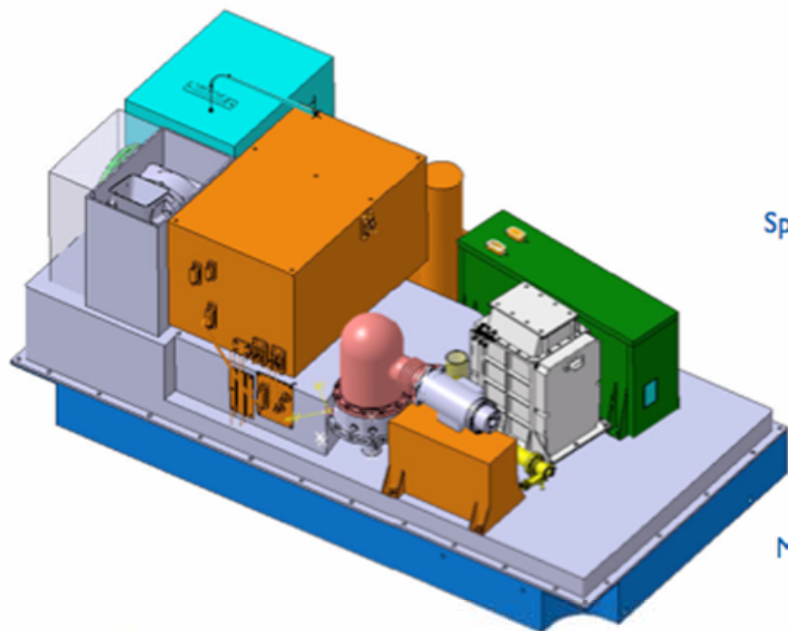
From 0 down to 2-m depth



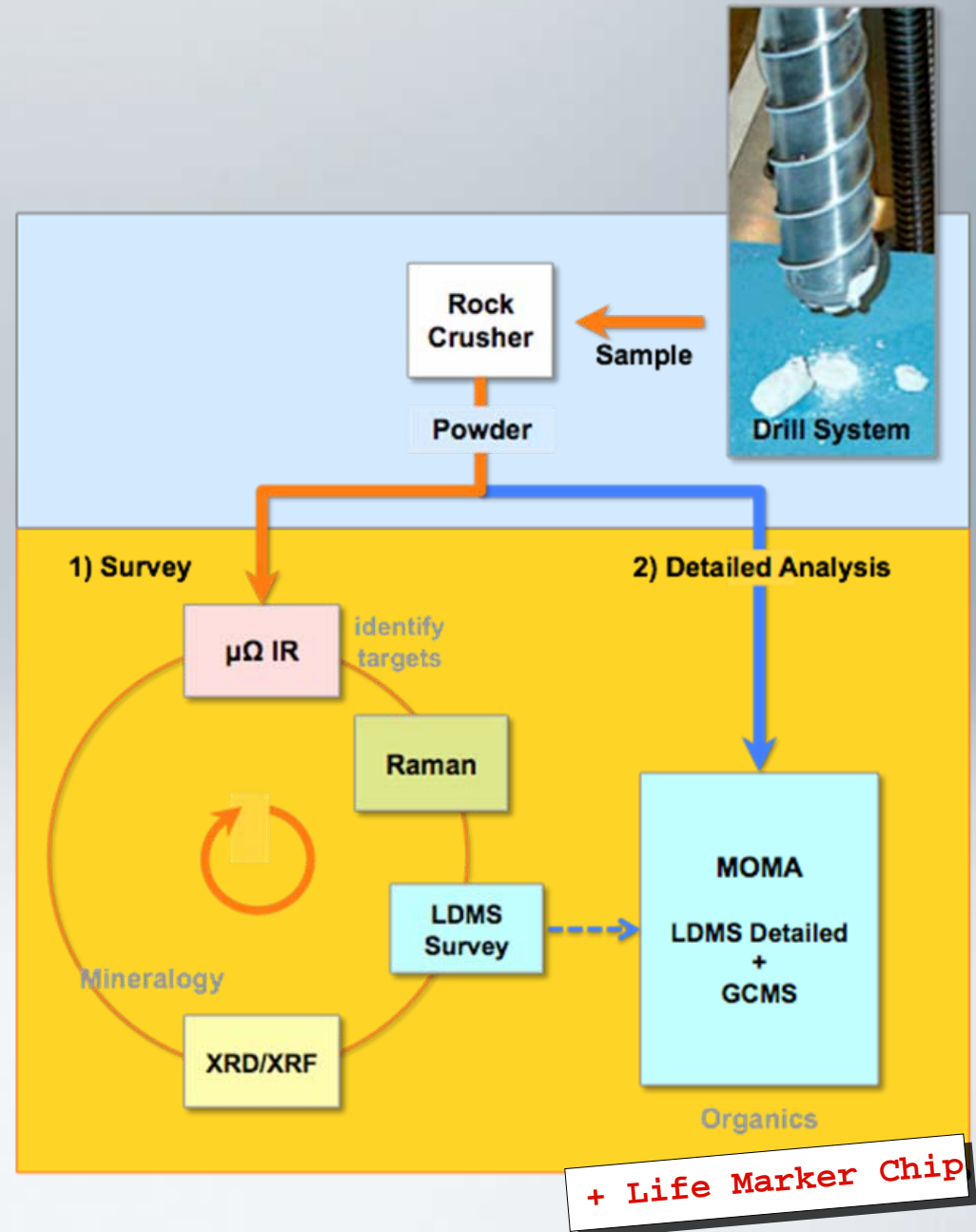
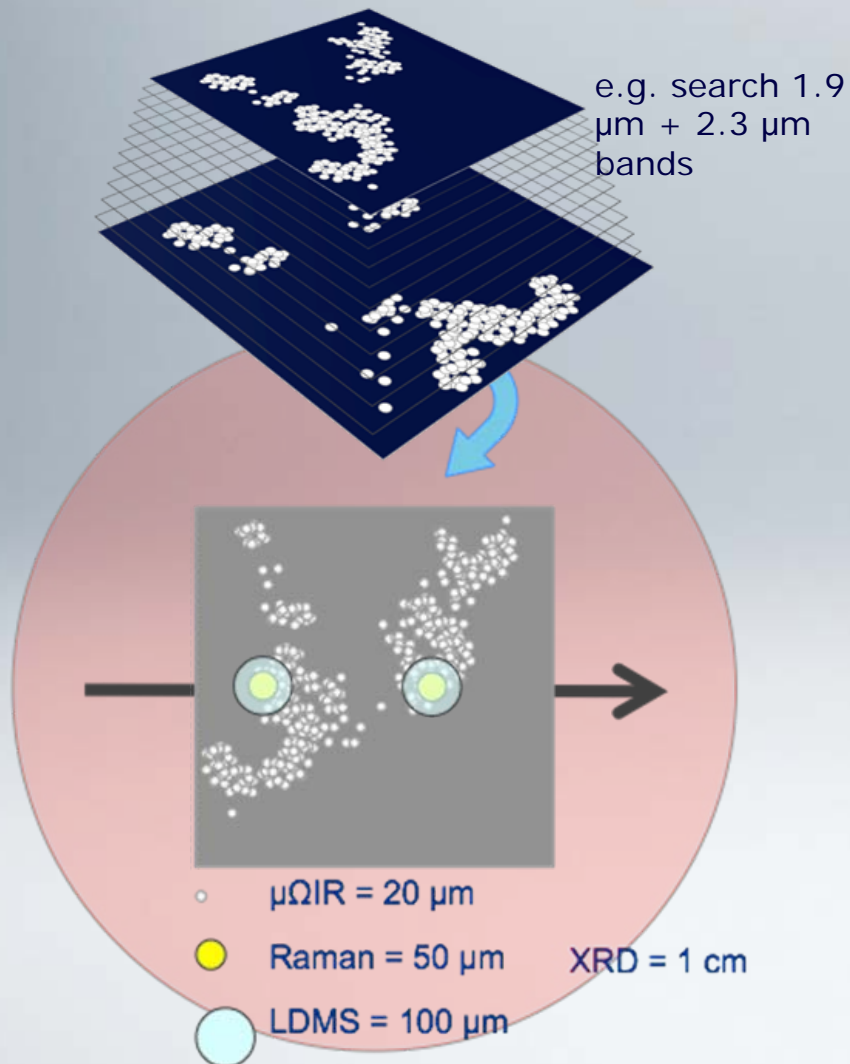
**DRILL** discharges sample into Core Sample Transport Mechanism (CTSM).  
PanCam **HRC** images sample.



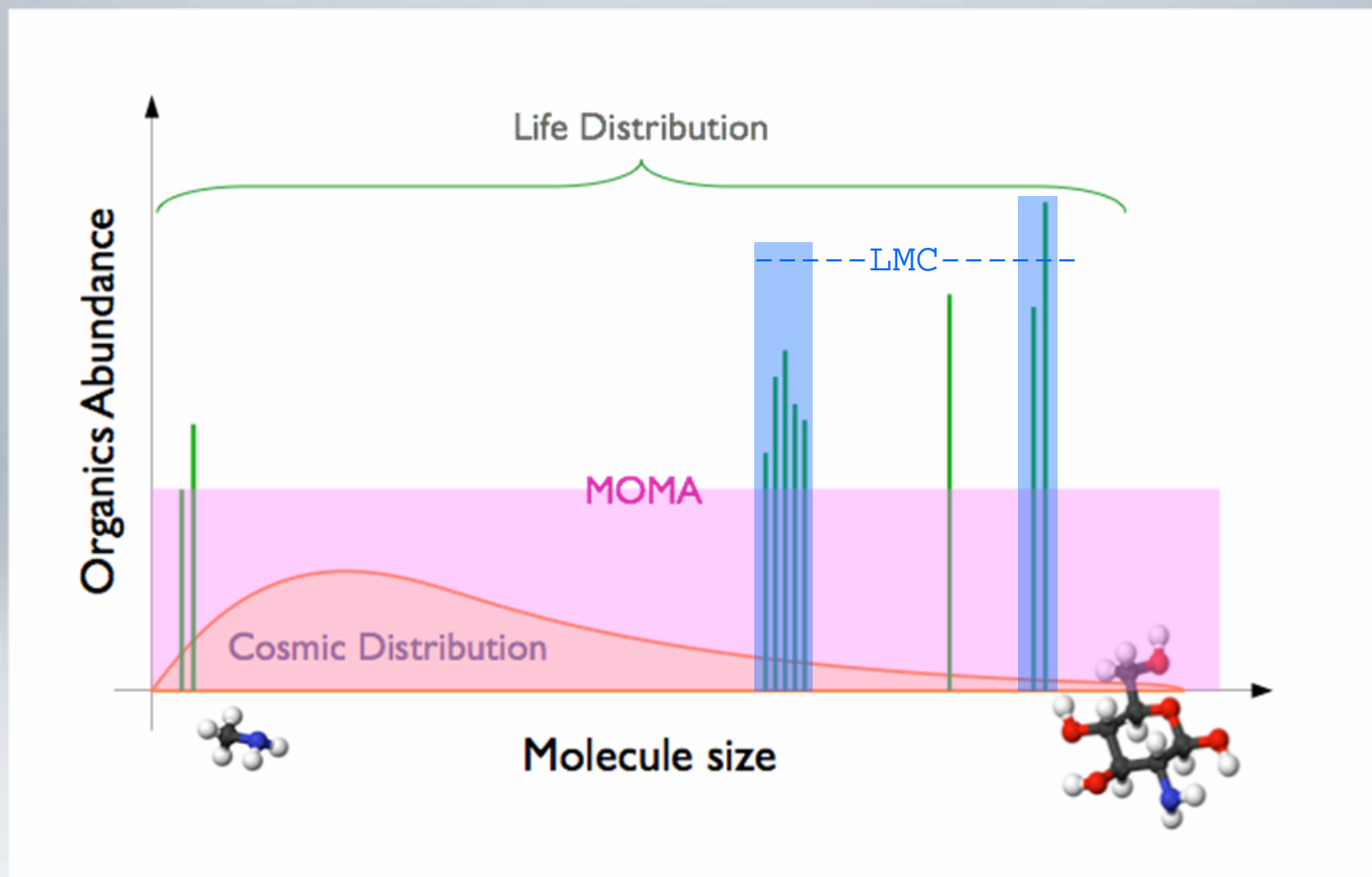




Use mineralogical + image information from  $\mu\Omega\text{IR}$  to identify targets for Raman and MOMA-LDMS.







Instrument Name	Description	Mass (kg) including maturity margin
PanCam (WAC + HRC)	Panoramic camera system	1.560
MOMA	LD-MS + Pyr GC-MS for organic molecule characterisation	6.100
MicrOmega IR	IR imaging spectrometer	0.960
Mars-XRD	X-ray diffractometer + X-ray fluorescence	1.480
Raman (internal)	Raman spectrometer	2.260
WISDOM	Shallow ground-penetrating radar	1.380
Ma_Miss included in 2.0-m drill	IR borehole spectrometer	

+ CLUPI  
+ Life Marker

chip

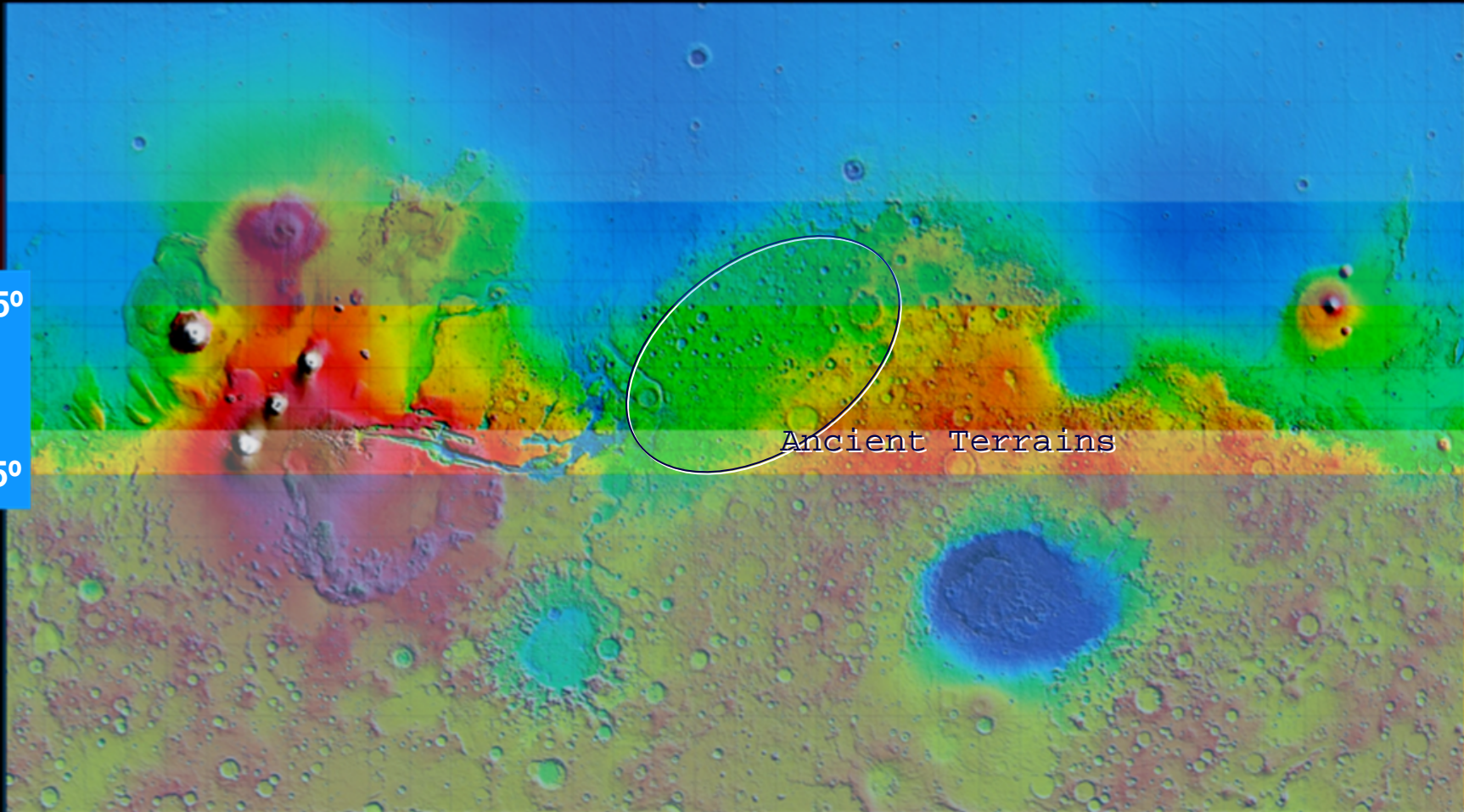
MOLA Topographic Map



+ 45°

+ 25°

- 15°



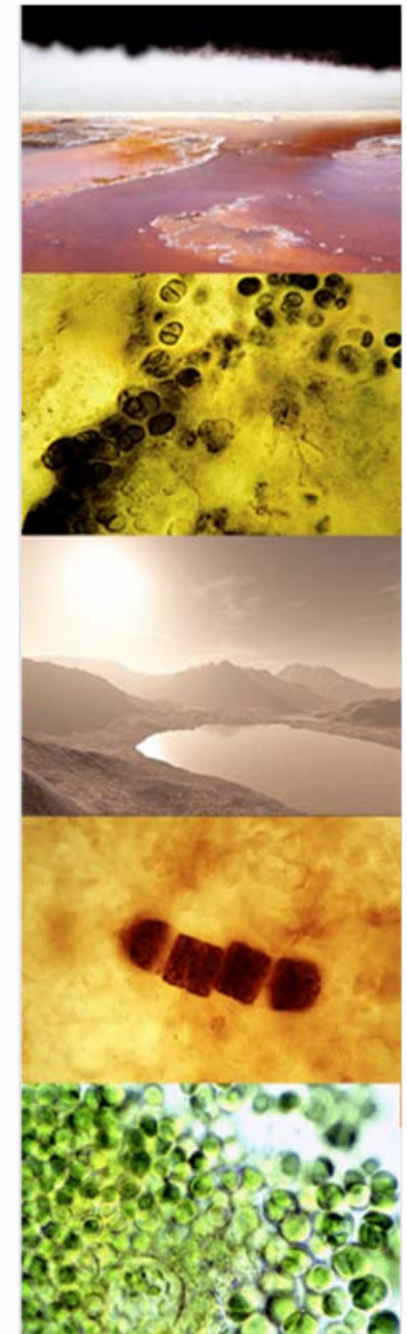


## ExoMars is a powerful exobiology mission:

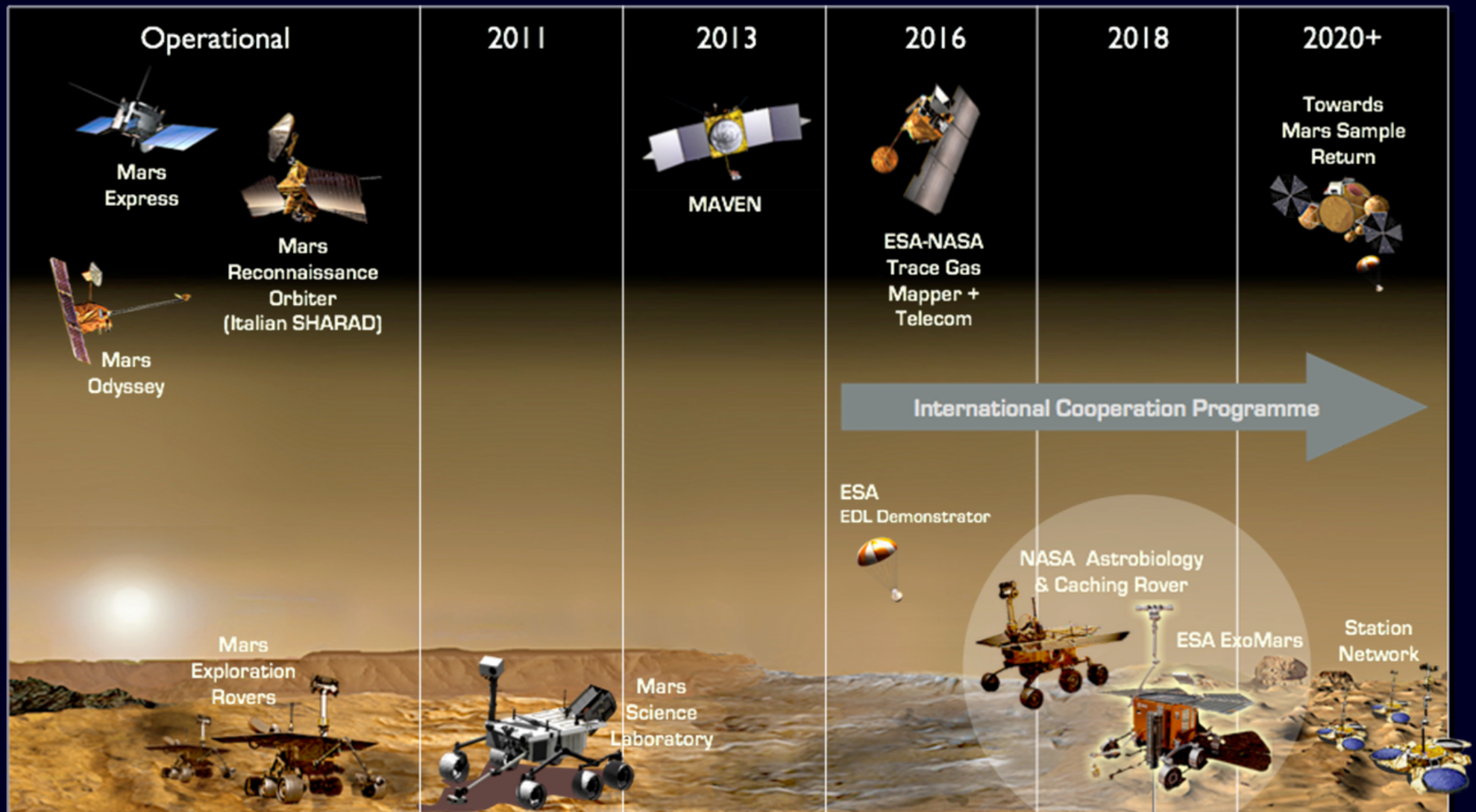
**We will search for signs of life...  
in places where nobody has looked,  
with instruments that no one has yet flown.**

- The proposed landing sites must cater to this overarching scientific goal. scientific goal.
- Proposed landing sites must contain evidence strongly suggestive of a past or of a past or present habitable environment.
- The prevailing outcrop mineralogy must be favourable for the long-term long-term preservation of organic molecules.
- Recently exhumed locations are particularly attractive —because of the long-of the long-term radiation shielding provided while they were buried. buried.
- Proposed sites must include several attractive targets within the ellipse. ellipse.
- Proposed sites must maximise opportunities for useful subsurface science science investigations.

**... and be safe for landing.**







➤ **MSL:** powerful rover; large 2-D mobility.

➤ **ExoMars:** next-generation instruments; 3-D access.

Following on the results of MSL, the ExoMars Rover is the logical next step in Mars surface exploration.