

High Resolution Stereoscopic Terrain Mapping Camera of Chandrayaan-1

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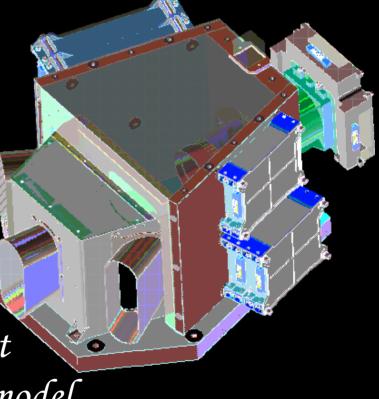


Terrain Mapping Camera (TMC)

Stereoscopic instrument in Panchromatic band for Topographic mapping with high spatial and altitude resolution.

- high resolution global map
- study regions of scientific interest
- could improve on Moon gravity model

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Aft

Fore

Detector plane

Swath : 20Km

Nadir

TMC Viewing geometry

Angular resolution: 50µrad (5m)

Along track FOV: $\pm 25^{\circ}$ (B/H=1)

Panchromatic band 500-850nm

Fore to Aft : 60.3s 56 pixels due to Moon rotation

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Orbital velocity

for six months

Imaging considerations

Chandrayaan-1 orbit : 100Km polar, non sun-synchronous

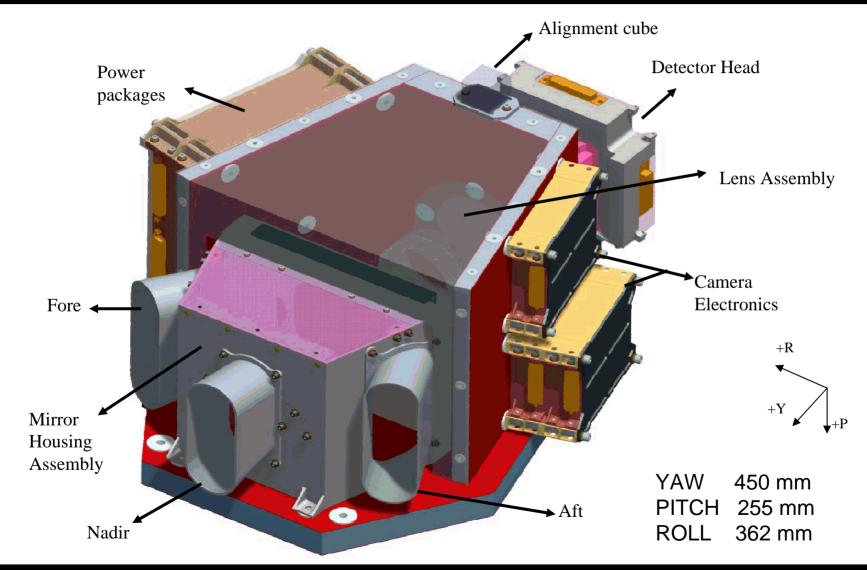
- scene illumination will undergo temporal variation
 to minimize illumination variation, imaging will be for sun angle of 0- 30°, Prime imaging time.
 2 time slots of 60 day/year separated by 4 months
- at other times Poles will be imaged
- 20min time for imaging I 50min for transmission (near side)

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Orbital velocity for six months *ICEUM9, Oct* '07



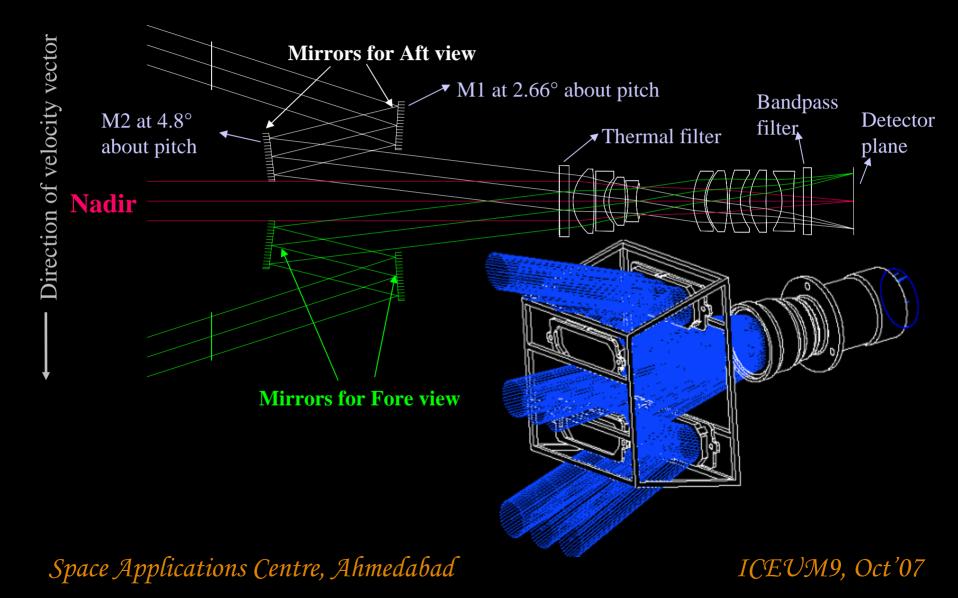




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TMC Optics





TMC Optics

- Spherical, Refractive optics
- Single lens assembly
- Folding mirrors for $\pm 25^{\circ} FOV$



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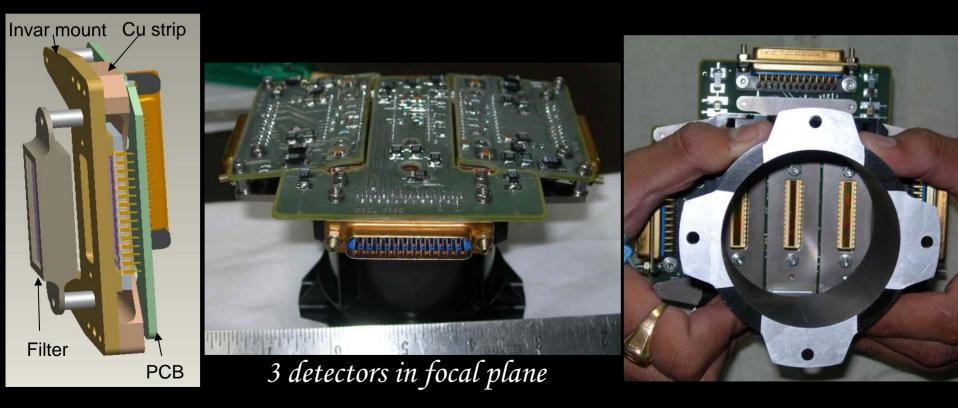


- EFL : 140mm, Fno. : 4
- Spectral range : 500 850nm
- Spatial frequency : 70 lp/mm



Detector Head

Detector - Active Pixel Sensor Linear, 7µ pixel, 4000 element, snapshot operation, Readout 3ms



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Camera Electronics

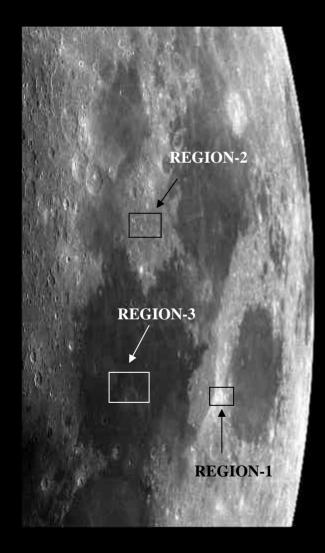
- Modular and Separate Electronics for 3 detectors
- Digital output : 12 bits, Serial with hot redundancy
- Data rate per detector : 16.3 Mbps
- Bit-sliding & loss less compression
- 10 bit transmission
- 4 programmable Gains
- 4 Exposure settings
- SNR improvement by increasing Ti upto 32 times

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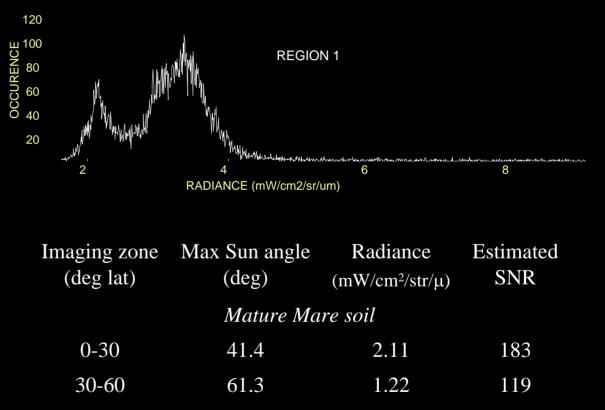




Radiance setting



Moon viewed by Cartosat-2



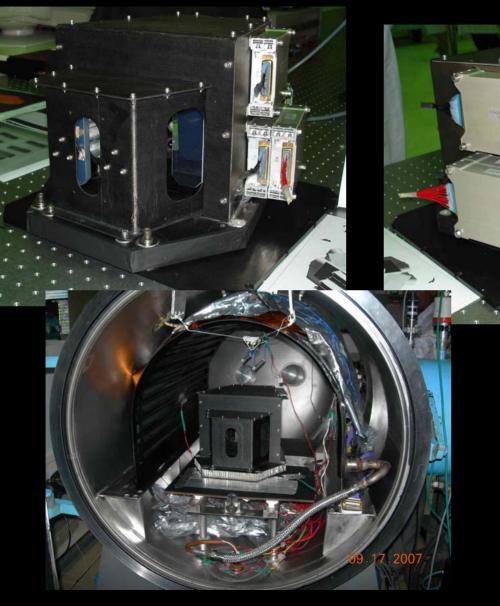
Fresh rock surface

0

0 14.2 615

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SNR : > 100 (±60° lat) MTF : > 10 Power : 3.7 W Weight : 6 Kg Op. Temp : 20 ±10 °C ICEUM9, Oct'07



Thank you

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