

Cross Scale Technology Reference Study

esa SCIENCE

Status update on ESA's Cross-scale Technology Reference Study

M.L. van den Berg, S. Cornara¹, F. Jubineau²,
C.P. Escoubet, M.G.G.T. Taylor, P. Falkner

*Planetary Exploration Studies Section
Science Payload & Advanced Concepts Office
ESA/ESTEC*

¹ DEIMOS Space S.L. ² Alcatel Alenia Space

deimos SPACE ALCATEL ALENIA SPACE
An Alcatel/Finmeccanica company

esa Planetary Exploration Studies Section
Science Payload & Advanced Concepts Office

Presentation February 27, 2007 Page 1

Cross Scale Technology Reference Study

esa SCIENCE

Outline

- Objective of the Cross-scale Technology Reference Study
- Study approach
- Study status
- Key mission requirements
- Mission architecture trade
- Baseline mission concept
- Identified mission drivers
- Conclusions and future work
- Summary

esa Planetary Exploration Studies Section
Science Payload & Advanced Concepts Office

Presentation February 27, 2007 Page 2

Objective of Cross-scale TRS

Study a possible plasma physics mission concept

- Scientifically meaningful
- Technically feasible
- Cost-efficient

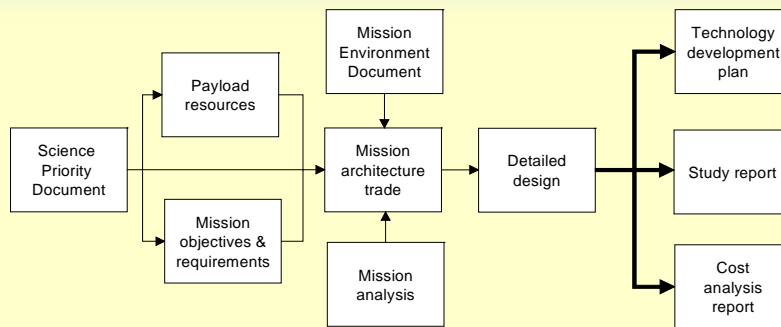
Through a detailed industrial system design study

Study documentation is a reference for

- Technology development roadmap
 - ✓ critical technologies
 - ✓ cost-reducing technologies
- Other mission concepts and proposal assessment

Technology Reference Studies help support longer term programme

TRS study outline



Sci-A & Sci-S
(if possible
with help from
community)

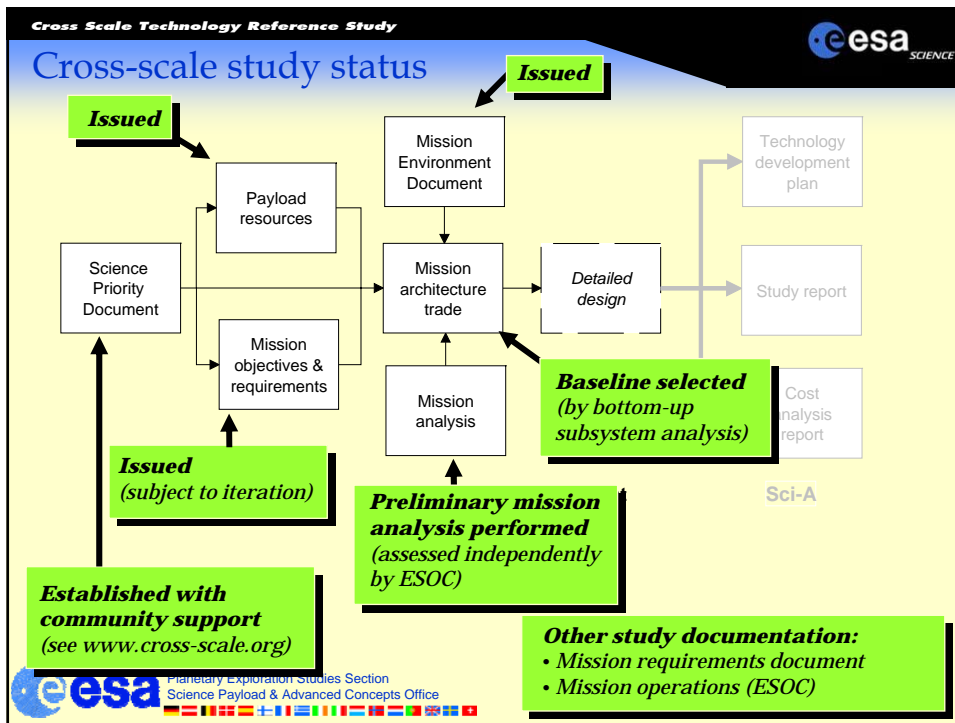
Sci-A

Industrial Assessment

Sci-A

Technology Reference Studies focus on:

- **Technological feasibility**
- **Fulfilment of science requirements**
- **Cost-efficiency**




Cross Scale Technology Reference Study

Mission objectives


Investigation of **fundamental space plasma** processes that involve **non-linear coupling** across **multiple length scales**

The key universal space plasma processes are:

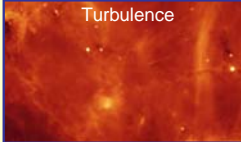
Reconnection



Shocks



Turbulence



All three processes:

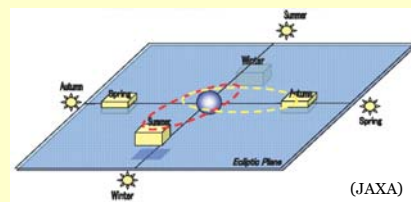
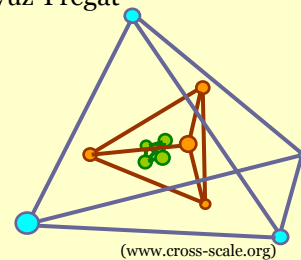
- ✓ Are dynamical
- ✓ Involve complex 3-D structured interaction between different length scales (electrons, ions, MHD fluid)
- ✓ Can be investigated in near-Earth space (bowshock, current sheet, magnetosheath)

Planetary Exploration Studies Section
Science Payload & Advanced Concepts Office

Presentation February 27, 2007 Page 6

Cross-scale TRS mission requirements (I)

- 8 – 12 spacecraft to be launched with a single Soyuz-Fregat
 - 1 – 4 on electron scale: 2 – 100 km
 - 4 on ion scale: 50 – 2,000 km
 - 3 – 4 on large scale: 3,000 – 15,000 km
- Spacecraft constellation scales are concentric
- Constellation passes through bowshock, magnetopause and magnetotail
 - Visit 'tail box' region at least once a year
- Constellations optimized at apogee and possibly perigee (for 10 Re)
- Range of constellation length scales is sampled at least once



Cross-scale TRS mission requirements (II)

Programmatics:

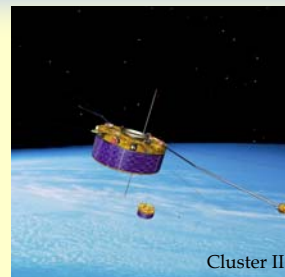
- ✓ Mission lifetime 3 – 5 years
- ✓ Technology development and demonstration horizon less than 5 years (TRL 5 in 2011)

Science data-rates (for complete constellation):

- ✓ On-board storage: > 1.5 Mbps × 2 orbital periods
 - Use of Hard-Disk Drive or SSMM (~100 Gbit per S/C)
- ✓ Downlink: 800 kbps (i.e. 65 - 100 kbps per S/C)

Inter spacecraft localization/synchronization:

E-scale	0.25 ms	125 m
Ion-scale	0.25 – 2 ms	1% of distance
Large scale	2 ms	1% of distance

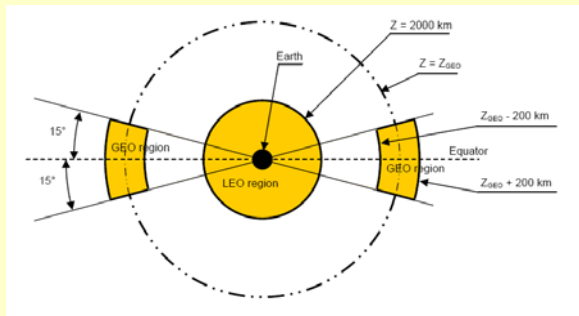


Cross-scale TRS mission requirements (III)

“European Code of Conduct for Space Debris Mitigation.”

No space segment shall enter the protected regions after mission completion, by taking one of the following precautions:

- Direct re-entry
- Limit orbital lifetime to less than 25 years
- Higher parking orbit



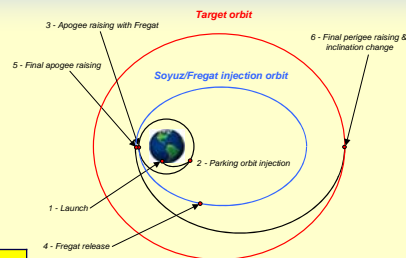
Hard requirement

- Impacts all Cross-scale S/C:
- Dispenser/transfer vehicle
 - Constellation S/C

Unless perigee above 6.7 Re

Mass analysis: Launch and transfer

- Launch by Soyuz-Fregat 2 (1b) from Kourou:
 - Mass into GTO: 3026 kg (TBC)
 - Effective mass into GTO: 2430 kg (20% system margin, 110 kg adapter)
- Operational orbits of interest:
 - Perigee: 1 Re + 500 km – 15 Re
 - Apogee: 25 Re (25 Re – 50 Re)
 - ‘Near equatorial’



Approximate dry mass in orbit (Isp = 325 s)

Orbit	Transfer ΔV (m/s)	Space debris ΔV (m/s)	Mass (kg)
10 Re × 25 Re × 14 °	1390	0	1570
10 Re × 25 Re × 14 ° (lunar resonances)	1115	0	1713
4 Re × 25 Re × 14 °	1005	185	1673
2 Re × 25 Re × 14 °	775	200	1790
1.4 Re × 25 Re × 14 ° (2500 km)	675	110	1900

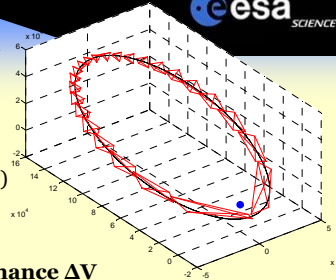
- Masses quoted are inclusive possible transfer vehicle, propellant tanks and propulsion system
- Deployment and reconfiguration ΔV not included in this table

**Clearly, if mass-constrained
10 × 25 Re and 1.4 × 25 Re
are the most attractive**

Mass Analysis: Constellation design

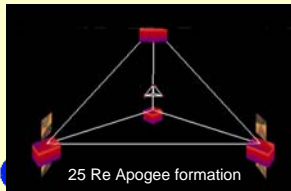
During operational phase propellant required for

- Deployment
- Spin-up and spin maintenance
- Constellation reconfiguration (medium+large: limited)
- Constellation maintenance (perturbations and drift)



Deployment/reconfiguration/maintenance ΔV

Orbit	Small scale ΔV (m/s)	Medium scale ΔV (m/s)	Large scale ΔV (m/s)	% Mass (large) (Isp = 308 s)
10 R _E × 25 R _E	5 m/s	50 m/s	200 m/s	~7%
4 R _E × 25 R _E	5 m/s	90 m/s	350 m/s	~11%
2 R _E × 25 R _E	10 m/s	115 m/s	450 m/s	~14%
1.4 R _E × 25 R _E	10 m/s	125 m/s	475 m/s	~15%



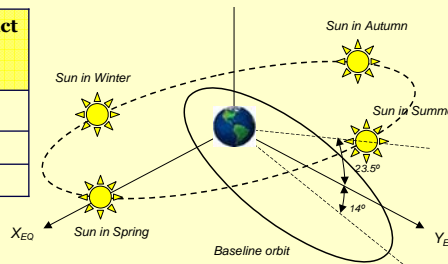
- If tetrahedron @ perigee is required, numbers becomes substantially higher
- Lower perigee:
 - ❑ Higher ΔV during mission
 - ❑ More frequent control manoeuvres (still only ~1 x per year)

Orbital analysis

Characteristics of orbits selected for preliminary mission analysis:

Orbit parameters	Period (days)	Time per orbit between 9 - 11 R _E	Time in tailbox per year	Average tailbox time (h)	Remarks
10 R _E × 25 R _E × 14° (max ΔV: 1315 m/s)	4.3	9.8% (2.9 km/s)	8.0% (> 1.2 km/s)	9 (0.6 - 16)	Most encounters (many away from apogee), at relatively high speeds
4 R _E × 25 R _E × 14° (max ΔV: 1540 m/s)	3.2	4.6% (2.1 km/s)	6.4% (~0.8 km/s)	11 (0.13 - 23)	
~1 R _E × 25 R _E × 14° (max ΔV: 1260 m/s)	2.8	4.2% (1.2 km/s)	3.5% (~0.5 km/s)	14 (1.1 - 33)	Fewest encounters, at relatively low speeds

Perigee	krad (5 y and 4 mm AL)	Max. eclipse time	Av. GS contact time	Contact %
10 R _E	6	3.3 h	14.5 h	47
4 R _E	70-90	5 h	13.6 h	48
~1 R _E	60	8 h	11.7 h	49



Science return optimization criteria

Science priorities:

1. Visit regions of interest
2. Maximization of number of S/C
3. Maximization of payload resources
4. Optimization of orbit

Note: Within financial envelope

Optimization of science products:

Typically, plasma science investigations are performed on:

1. Detailed analysis of events that are constrained in time (<~2 hr)
2. General space plasma characteristics along the orbit

Science return optimization:

1. Allow different P/L configurations on identical S/C
 - Use standard slots and interfaces for e.g. particle instruments
 - Design all S/C for a standard 'maximum' P/L configuration
2. Only downlink 'useful' science data:
 - Nominal data over complete orbit
 - High-data rate products for selected time slots:
 - On-board triggering (difficult for constellation 'events')
 - On-ground selection based on nominal data (requires on-board memory and streamlined Mission Ops/Science Ops)

Mission architecture trade

Launch with SF 2-1b from CSG.

- Initial orbit lower than GTO (20,000 km)

Transfer to operational orbit by dispenser-like transfer vehicle

- Reduction of mission operations complexity
- Mass optimization (propulsion staging, constellation S/C design)
- Scalable design (operational orbit vs number or mass of S/C)
- Payload accommodation (axial antenna)

Operational orbit 1.4 x 25 R_E

- Maximization of number of S/C (10 S/C in baseline orbit)
- Space Debris policy

Identical spacecraft

- Cost optimization (design, AIV and Ops)

Nearly identical payload

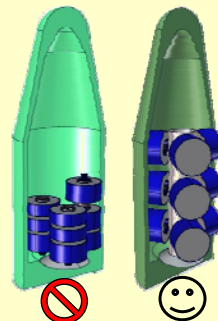
- Identical P/L interfaces to S/C for a set of possible P/L configurations
- Requirements on P/L autonomy and reliability

Communication architecture

- Direct link of individual S/C to G/S

Operations

- Cost optimization (see also above)
- Automated downlink
- S/C autonomy/reliability vs operational complexity
- S/C memory vs operational complexity ('data'-selection)



Dispenser preliminary design

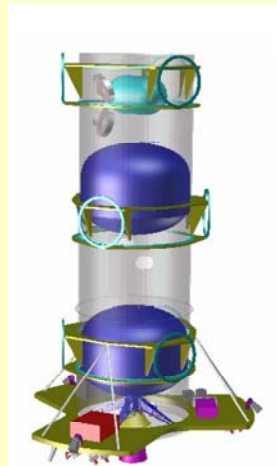
- Structure based on SpaceBus 4000
 - ✓ Existing design (cost-efficient)
 - ✓ Qualified up to 5,000 kg
 - ✓ Low weight CFRP
 - ✓ Use of existing propellant tank configurations



(www.saabgroup.com)

Dispenser characteristics:

- Transfer to operational orbit, deployment, de-orbit
- Independent operation:
 - ✓ AOCS (3-axis)
 - ✓ Comms (S-band)
 - ✓ CDMU
 - ✓ Power (3.5 hr eclipse)
- Safe mode: slowly spinning



Scaleable design

S/C preliminary design

Key characteristics of preliminary baseline:

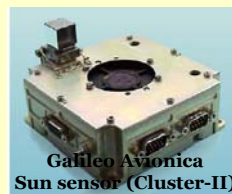
Number of S/C	10 (4 large, 4 medium, 2 small scale)
Dimension	~1.5 m (Ø) × ~1 m (height)
Spinning rate	20 – 40 rpm
Total mass	145 – 160 kg (depending on scale)
Dry mass (excl. P/L)	106 kg
Power	160 W
Communication	X-band, 10 W (RF), omnidirectional, variable data-rate (up to 3 Mbps)
On-board memory	256 Gbits SDRAM/DDRAM
AOCS	Star mapper, sun sensors, bipropellant thrusters
Max. P/L mass	42 kg (excl. S/C ranging)
Max. P/L power	30 W (exc. S/C ranging)
P/L / total dry S/C	10 - 30% (incl. S/C ranging)

Key spacecraft mass drivers

- Identical S/C
- Power (downlink requirements, maximum P/L power)
- Accommodation of maximum P/L mass (42 kg)



Saab-Ericsson antenna (Herschel/Planck)



Galileo Avionica Sun sensor (Cluster-II)



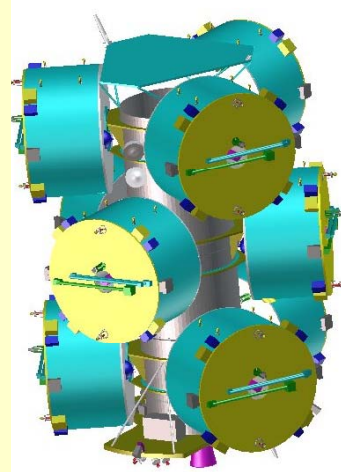
TNO-TPD Star Mapper (Cluster-II)

Launch stack

Projected mass budget:

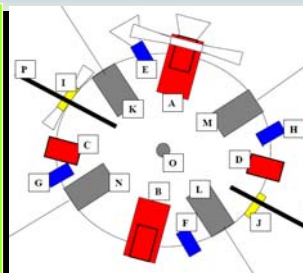
Item	Number	Mass each (kg)	Remarks
Large scale S/C	4	144	13 kg P/L
Medium scale S/C	4	158	34 kg P/L + S/C ranging
Small scale S/C	2	162	42 kg P/L + S/C ranging
S/C total	10	1532	
Dispenser	1	515	Dry mass
Propellant	1	1157	Only for transfer
TOTAL		3204	
Launch capacity		3885	Into 20,000 km, adapter subtracted
MARGIN		681	21% system level margin (20% required)

Preliminary design



Possible payload distribution

Instrument	Location of instruments				
	e - scale #1	e - scale #2	ion scale #1	ion scale #2-4	Large scale
DC Magnetometer	P	P	P	P	P
AC Magnetometer	Q	Q	Q	Q	Q
Wire boom antenna	KLMN	KLMN	KLMN	KLMN	-
Axial antenna	O	O	-	-	-
Electron ESA	EFGH	-	-	-	-
Ion ESA	-	EFGH	-	-	-
Electron/Ion ESA	ABCD	ABCD	CD	ABCD	A
Ion composition	-	-	AB	-	-
Hot plasma particle composition	-	-	-	EF	-
Solid State Telescope	-	IJ	-	IJ	I



Key requirements (feasibility TBC):

- Limitation of payload instrument modes
- Autonomous instrument operation (also during eclipses, radiation belt, solar flare)
- Speedy initialization/recovery procedures (maximum 1 day)

Identified mission drivers

Driver	Impacts
Operational orbit	Launch mass
Space debris mitigation	Launch mass, S/C design, mission lifetime
Large scale constellation (re)configuration	Propellant, S/C design, mission operations
Number of satellites	Launch mass, AIV, mission operations
Number of different satellites	AIV, mission operations
Payload mass + power	Launch mass
Instrument modes	Operations
On-board data storage	Launch mass, mission operations
Downlink rate	Communication system, power system, ground system

Identified technology requirements

Technologies	Remarks
Small/medium scale synchronization	Real-time inter-S/C system for spinning satellite
On-board memory	Hard-Disk-Drive would allow large amount of on-board data storage
Low-resource X-band transponder and amplifier	Applicable for most of future (science) mission concepts
TO BE CONTINUED	

Conclusions

Cross-scale Technology Reference Study is work in progress

- ✓ Mission analysis has been performed
- ✓ Mission architecture trade concluded
- ✓ Mission architecture baseline selected

Next steps

- ✓ Refined spacecraft design
- ✓ Mission operations
- ✓ Programmatics

➤ **Technology development plan**



End