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# **STE-QUEST – Space Geodesy Mission for Terrestrial and Celestial Reference Frame Realization**

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# Content

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- STE-QUEST as Space Geodesy Mission for Terrestrial and Celestial Reference Frame Realization
- GRASP Mission from JPL (Terrestrial Reference Frame)
- Reference Frame Requirements
- First SLR Double-Differences: The mm-SLR!
- Kinematic and Dynamic ITRF/ICRF Realization with STE-QUEST
- Ground VLBI with STE-QUEST
- Space VLBI with STE-QUEST Clock
- STE-QUEST and GAIA
- Survey of Extragalactic Sources at S/X/Ka/.../(W)-band (higher bands)
- Metrology link for operational relativistic geodesy

## STE-QUEST



### Fundamental Physics

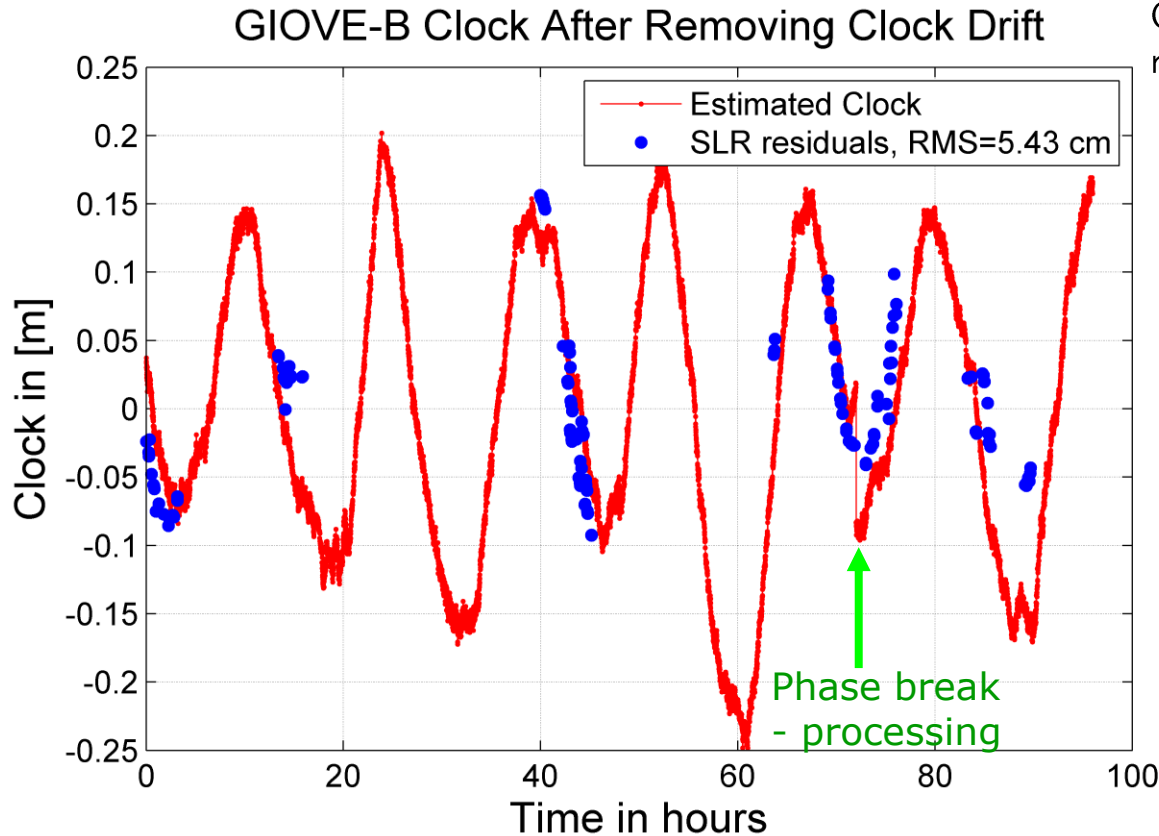
- High-accuracy Relativistic Geodesy

### Space Geodesy

- **VLBI:** STE-QUEST  $\mu$ -Metrology Link – (S,X,Ka)
- **Satellite Laser Ranging**
- **GNSS** - AGGA-4 chip: Galileo, GPS, GLONASS, Beidou
- **DORIS** (at higher altitudes)
  - GNSS receiver tracking both GNSS/DORIS signal
  - nadir flat phased-array antenna (GNSS/DORIS)
- **Space VLBI with STE-QUEST Clock (link to GAIA)**
  - with phased-array antenna – VLBI/GNSS (top)
  - possible optical data link

No-Additional Payload – just enhancing proposed payload

# GIOVE-B Clock Against SLR-Satellite Laser Ranging



Only time bias and time drift removed!

**First time:**  
GNSS clock geometrically maps the radial orbit error!!!

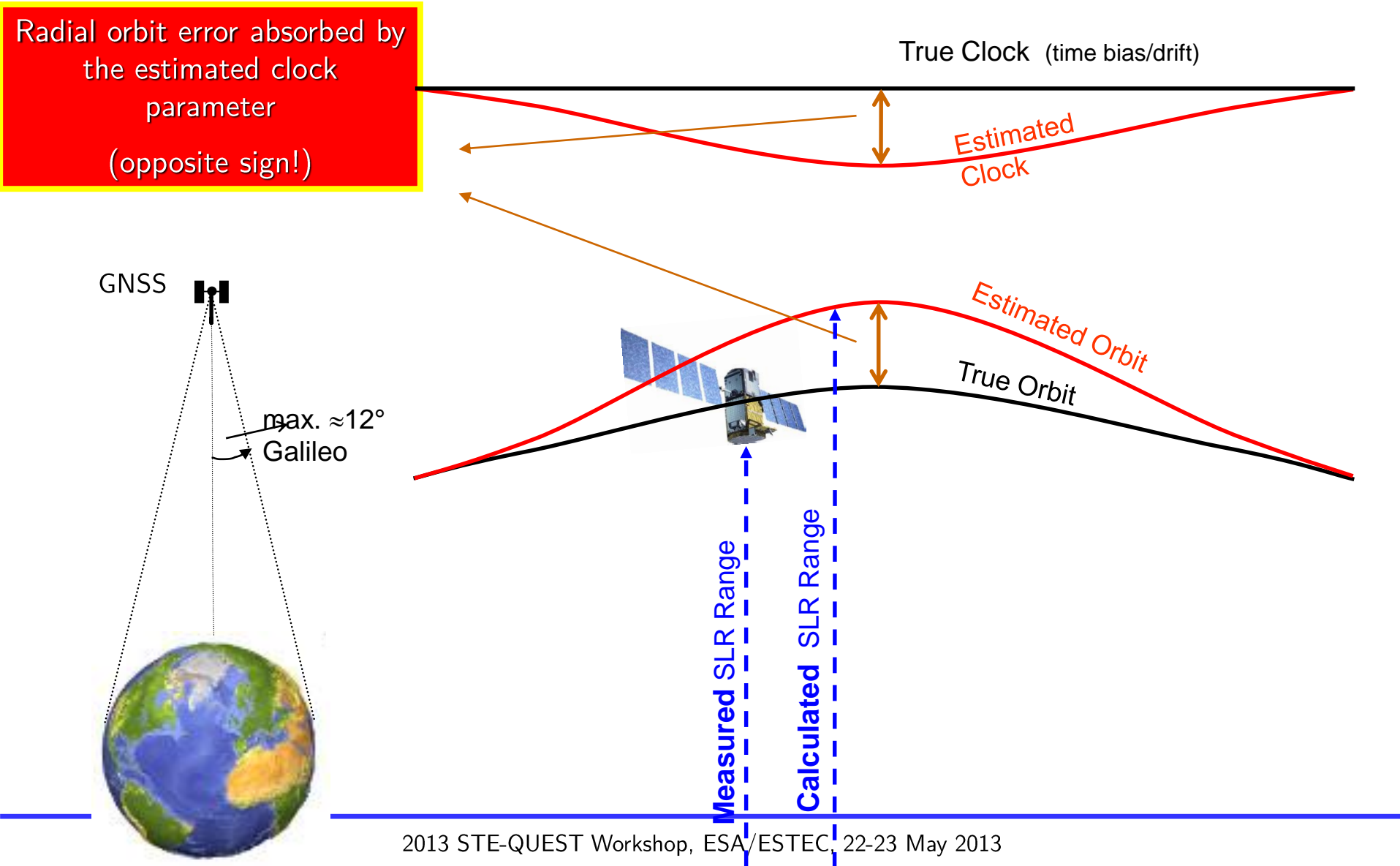
**Clock improves and stabilizes the orbit!**

Agreement between GIOVE-B clock and SLR is fantastic  
**1-2 cm only!!!** (with limited ground network)

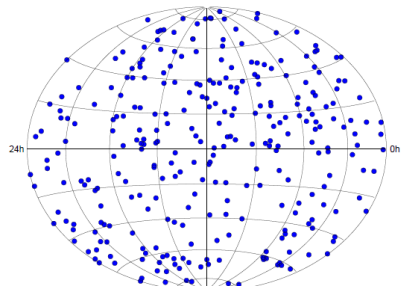
**(Svehla et al., 2010)**

Figure fully authorised for the publication by the Galileo Project

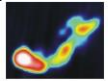
# Orbit and Clock Dependency



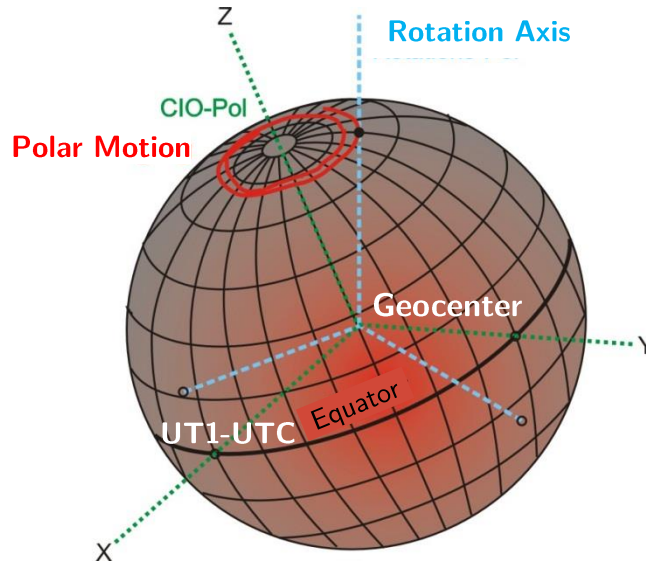
# Terrestrial and Celestial Reference Frames



Extragalactic Sources



Quasar



Mond

LLR

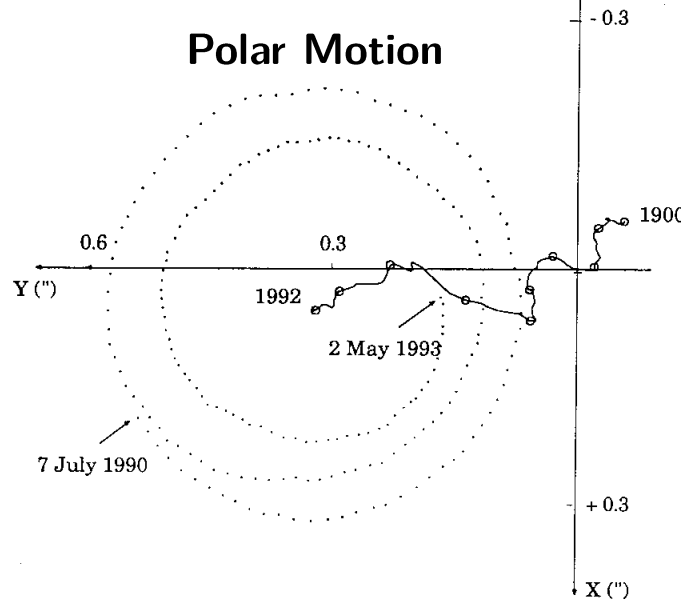
VLBI

GPS

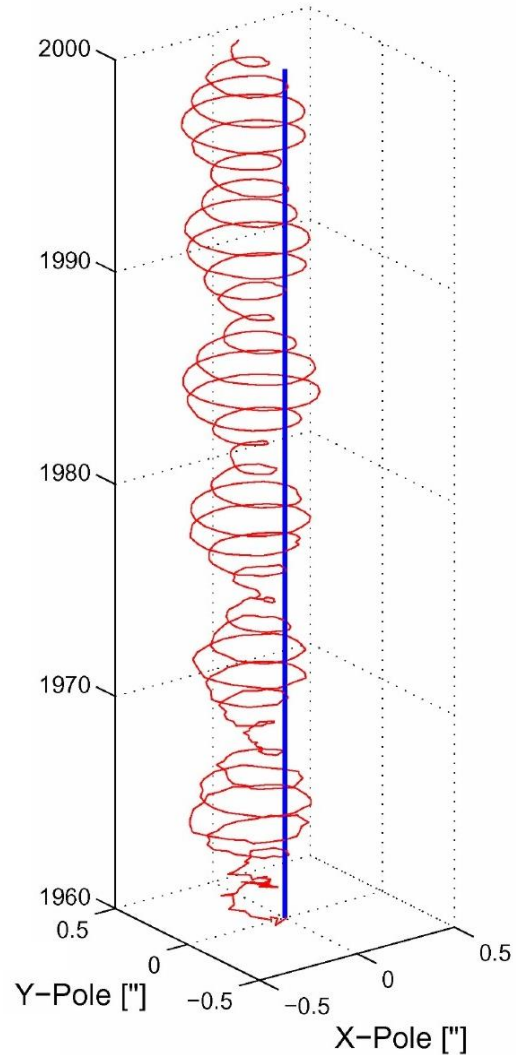
SLR

DORIS

Polar Motion



VLBI/SLR/GPS, 1960-2000



# The Geodetic Reference Antenna in Space (GRASP): A Mission to Enhance the Terrestrial Reference Frame

**STE-QUEST is GRASP mission in highly elliptic orbit + Space VLBI**



## The GRASP Spacecraft

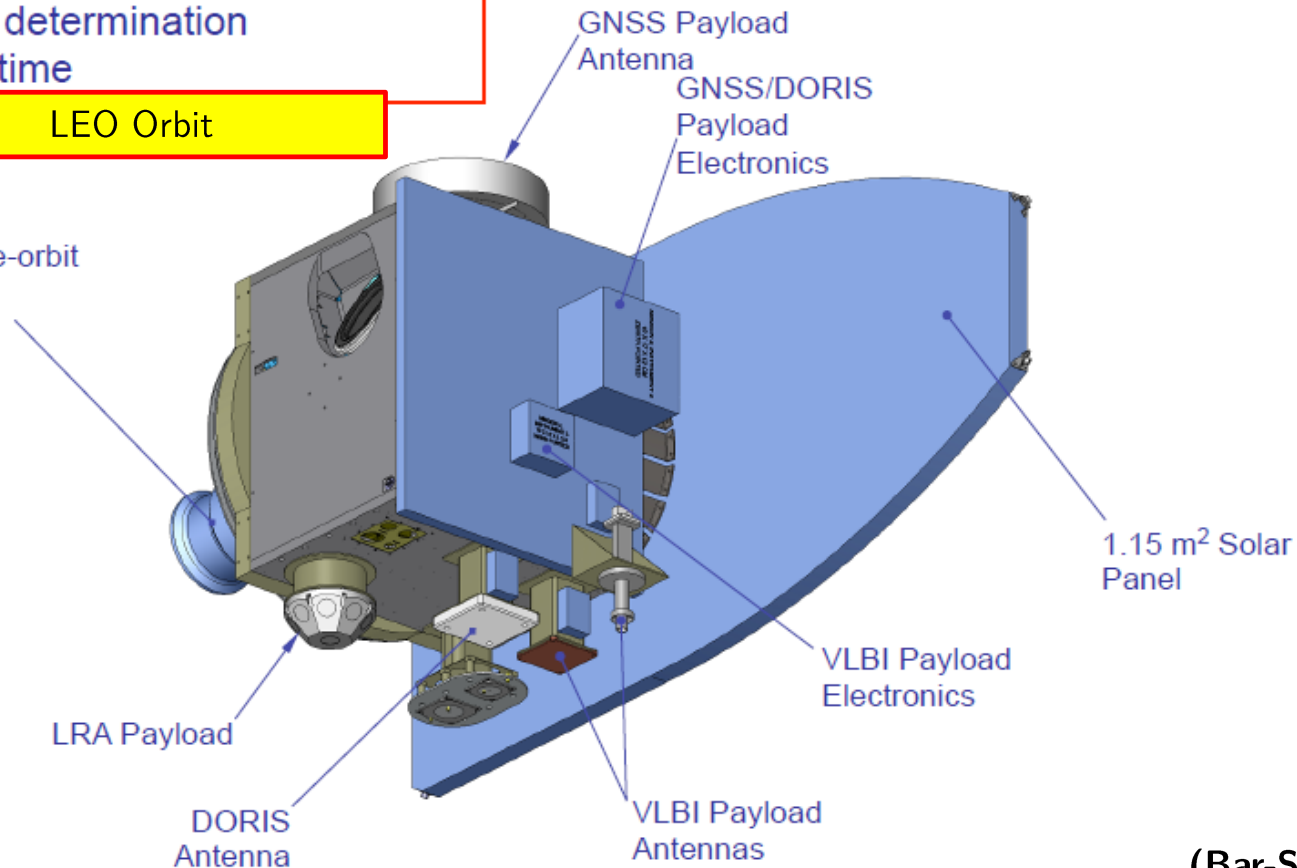


PI: S. Nerem

Orbit: 850x1350 Sun-synch  
Collocate sensors and CM to 1 mm  
1 mm orbit determination  
3 years lifetime

**LEO Orbit**

Star 6B De-orbit SRM



### Science Team:

- Altamimi
- Bar-Sever
- Biancale
- Chambers
- Gross
- Haines
- Lemoine
- Ma
- Murphy
- Pavlis
- Petrachenko
- Ries
- Schuh
- Schutz
- Wahr
- Willis

(Bar-Sever et. al 2012)



# GRASP Mission - JPL

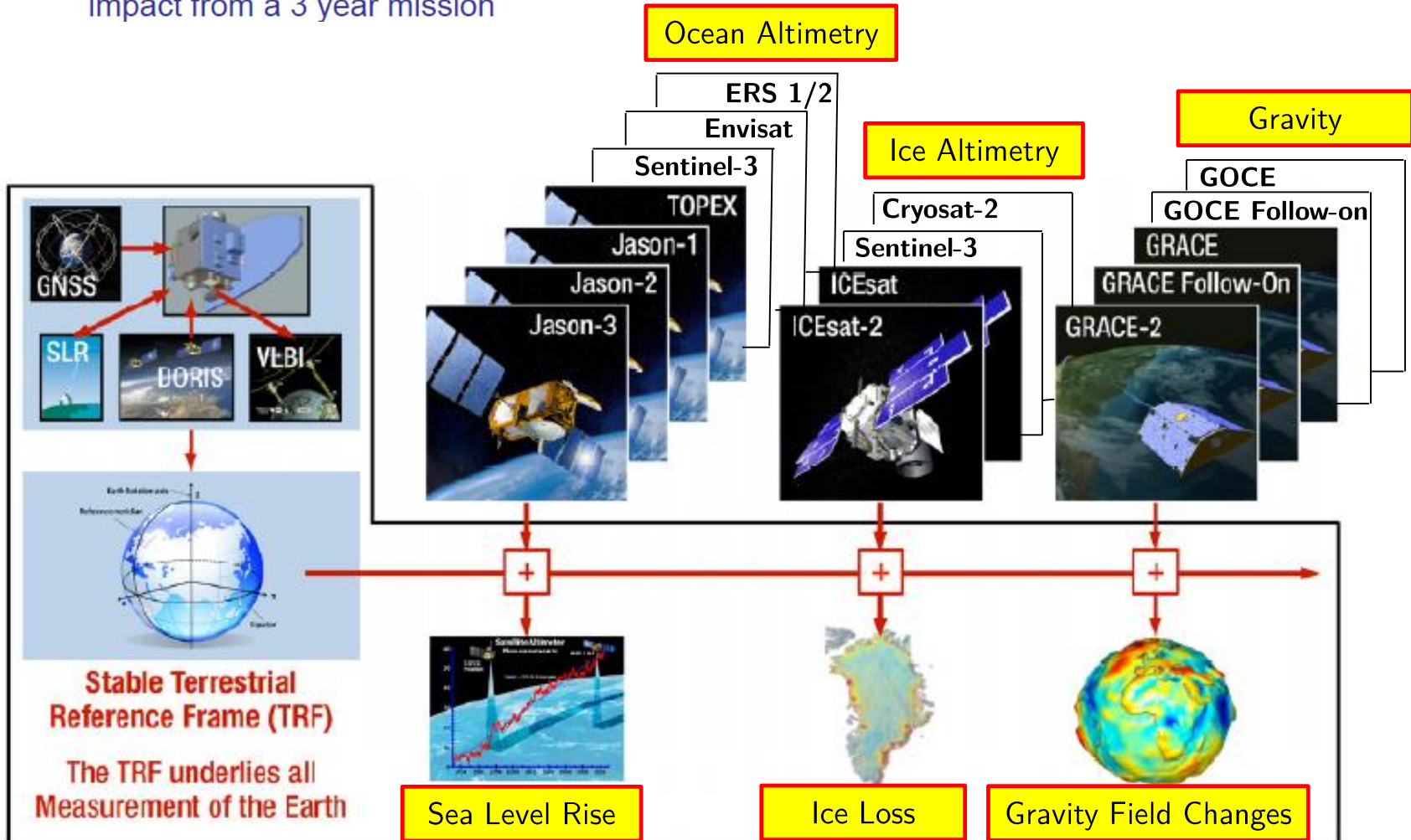


Collocate all the geodetic technique on a supremely calibrated satellite

- Use as reference for all GNSS antennas (space and ground)
- Determine ground collocation at arbitrary baselines

(Bar-Sever et al., 2012)

GRASP enhances science from past and future Earth science missions; ~30 year impact from a 3 year mission



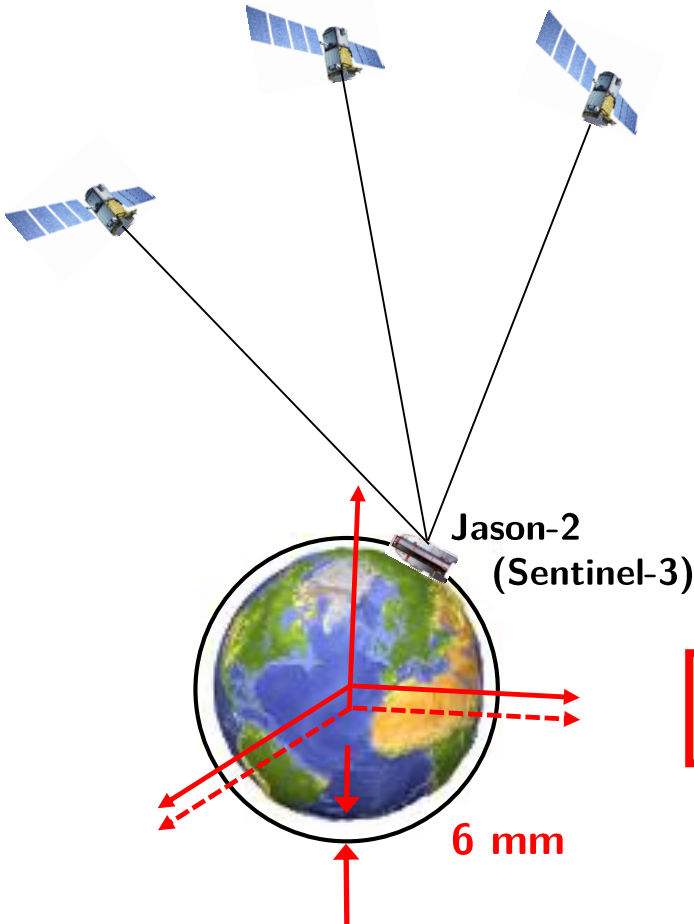


# STE-QUEST - Space Geodesy Mission

- **Terrestrial Reference Frame Realization** (STE-QUEST as GRASP Mission from JPL in highly elliptic orbit)
- **Celestial Reference Frame Realization** Ground/Space VLBI. Survey of extragal. sources at higher frequencies
- To meet GGOS (Global Geodetic Observing System) requirements for terrestrial reference frame of the Earth:  
**1 mm accuracy and 0.1 mm/yr stability of the TRF:**
  - significantly improve **satellite altimetry and tide gauge records** of **global mean sea level rise** by using highly accurate TRF from the STE-QUEST mission
  - contribute to **mass transport in polar regions** (ice mass loss) by referencing altimetry (Cryosat, ICESat) and gravity data (GRACE, GOCE) to the common TRF
- Determination of the **long-wavelength variability in the gravity field** of Earth (central term and J2) that are either not observed or poorly observed by GRACE (e.g. J2)
- Monitoring of the Earth rotation and orientation parameters making use of the highly elliptical orbit of the STE-QUEST mission (UT1 etc.) and VLBI tracking from the ground (quasars/GNSS satellites)
- Improvements in orbit accuracy of GNSS satellites (Galileo, GPS, GLONASS...) by one order of magnitude
- Provision of a common time scale for all space geodesy techniques (VLBI, GNSS, DORIS and SLR)
- Dissemination of TRF and time anywhere on Earth or in space
- Advanced modelling of solar radiation pressure, a new way to cope with non-gravitational forces on a satellite
- High-accuracy relativistic geodesy  $<1$  cm accuracy (using STE-QUEST metrology link)

# Terrestrial Reference Frame Geocenter Monitoring

GNSS satellite (GPS)



## Weekly Geocenter Estimates

Week 1	Week 2	Week 3
dx = -0.83 mm	dx = -1.78 mm	dx = -1.72 mm
dy = -0.94 mm	dy = -1.67 mm	dy = -1.22 mm
<b>dz = -5.90 mm</b>	<b>dz = -5.75 mm</b>	<b>dz = -5.60 mm</b>
rx = 0.021 mas	rx = 0.067 mas	rx = 0.059 mas
ry = 0.052 mas	ry = 0.055 mas	ry = -0.011 mas
rz = -0.051 mas	rz = -0.077 mas	rz = -0.051 mas
scale = 0.13 ppb	scale = 0.14 ppb	scale = 0.16 ppb

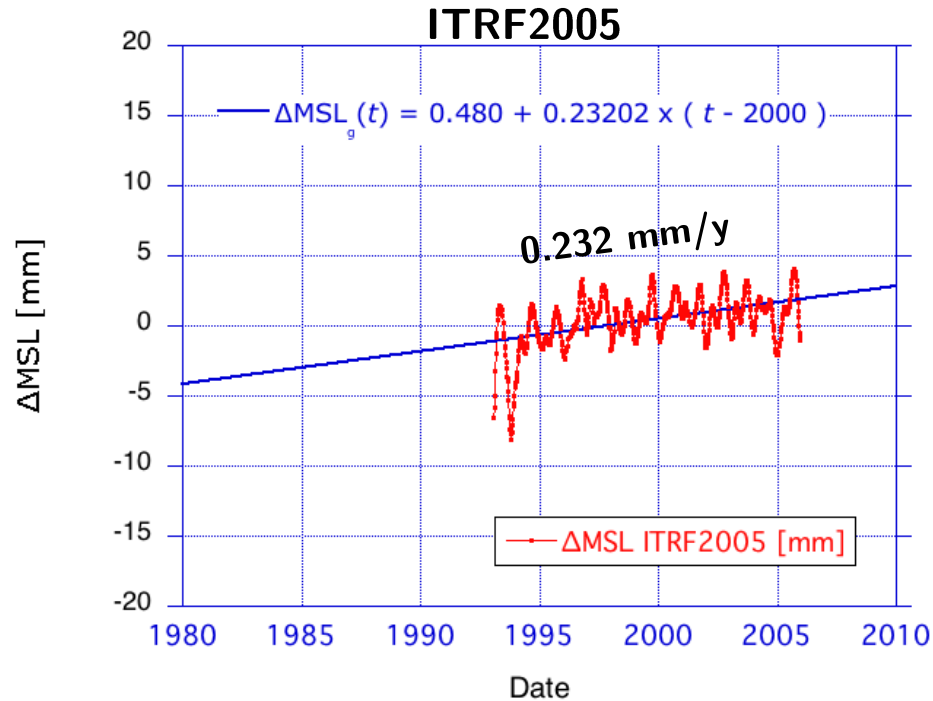
The **6-mm effect** in the Geocenter is well above the GGOS Requirement of **1 mm accuracy** and the sea level rise of **3 mm/y**

(Svehla et al., 2010)

**JASON-2 + GPS Constellation**  
**(GPS+SLR+DORIS)**

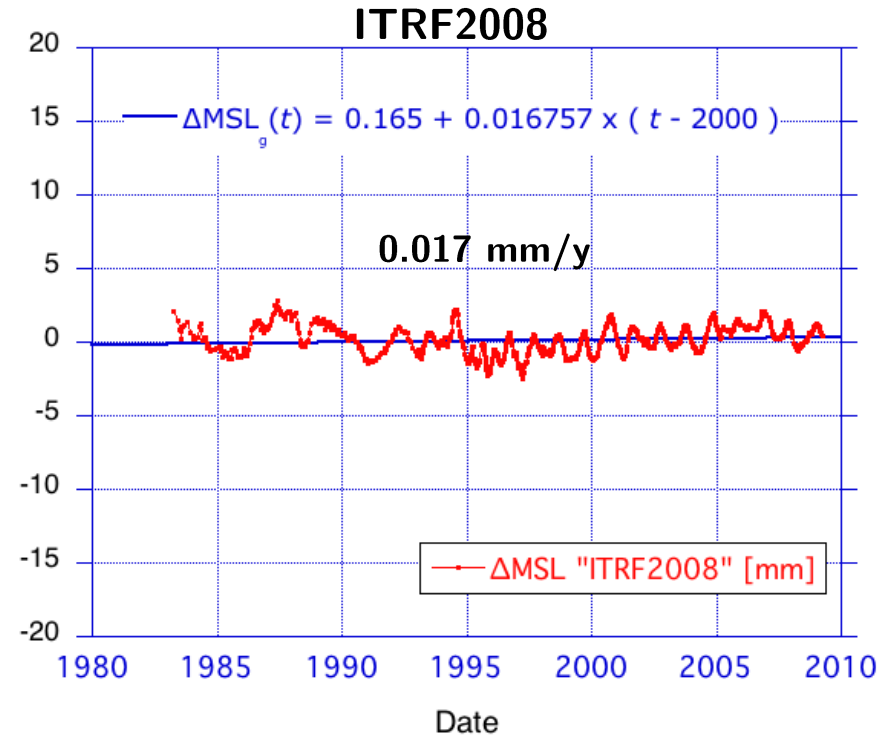
# MSL Rate Differences Due to TRF Error

Mapping the Error in the Z-axis Rate of the ITRF onto the Mean Sea Level Rate



ITRF2005 used SLR data over 1993 - 2004

Rate bias: **0.232 mm/y**



ITRF2008 used SLR data over 1983 - 2008

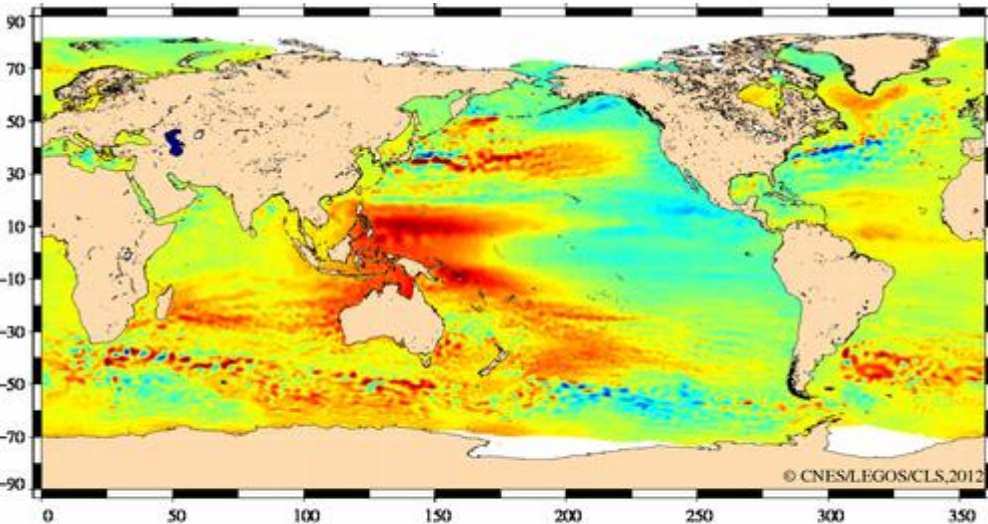
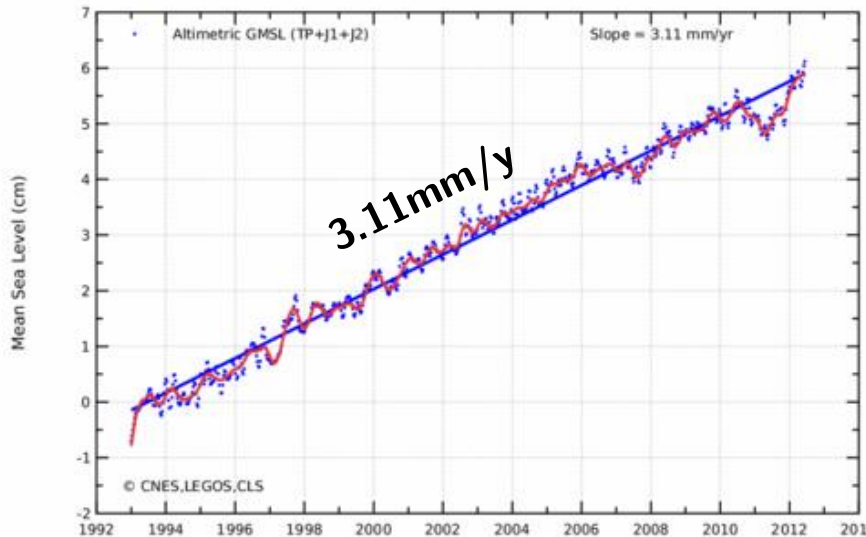
Rate bias: **0.017 mm/y**

(Pavlis et al., 2012)

# Reference Frame Requirements and Global Mean Sea Level

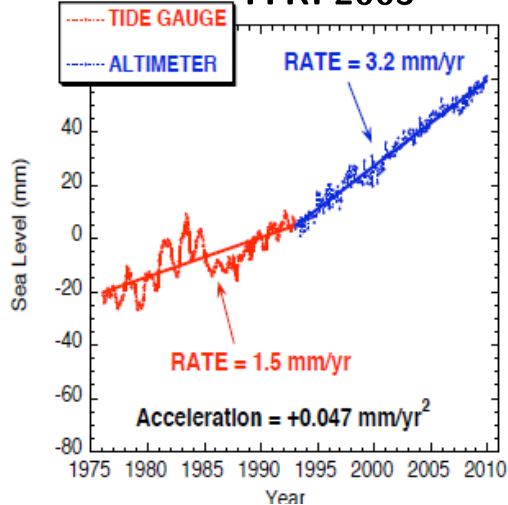
Globally averaged rate: 3.11mm/y

Regional rates:  $\pm 12$ mm/y



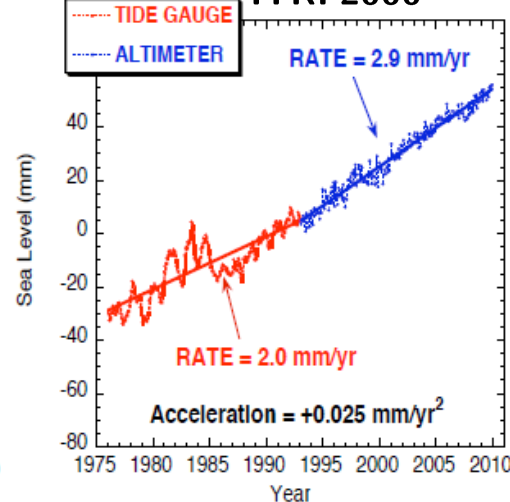
-12 -9 -6 -3 0 3 6 9 12  
Regional MSL trends from Oct-1992 to Apr-2012 (mm/year)

ITRF2005



(Church and White, 2011)

ITRF2000



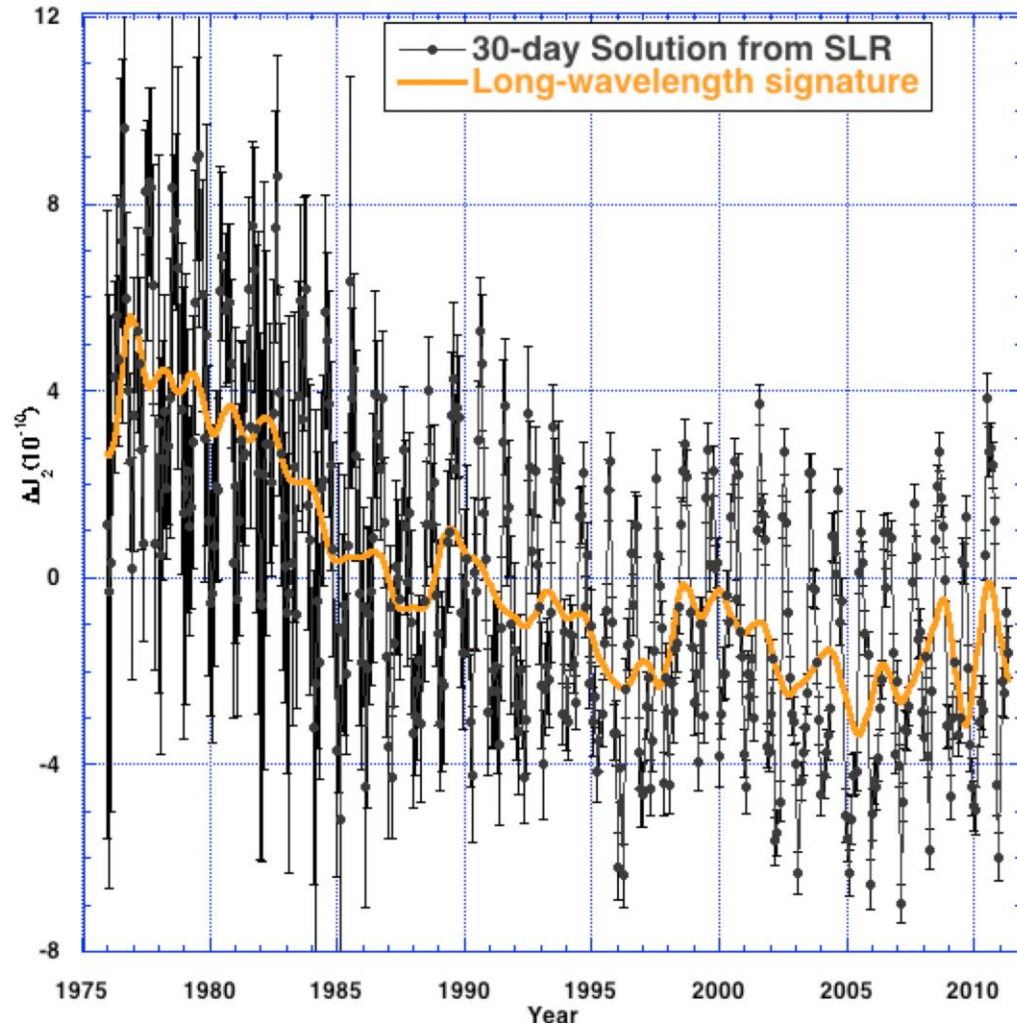
(Bar-Sever, 2012)

## GGOS Requirements for Terrestrial Frame

- < 1 mm accuracy
- < 0.1 mm/y stability

**We need to improve ITRF performance by a factor of 10-20!**

# J<sub>2</sub> Gravity Field Variations from SLR



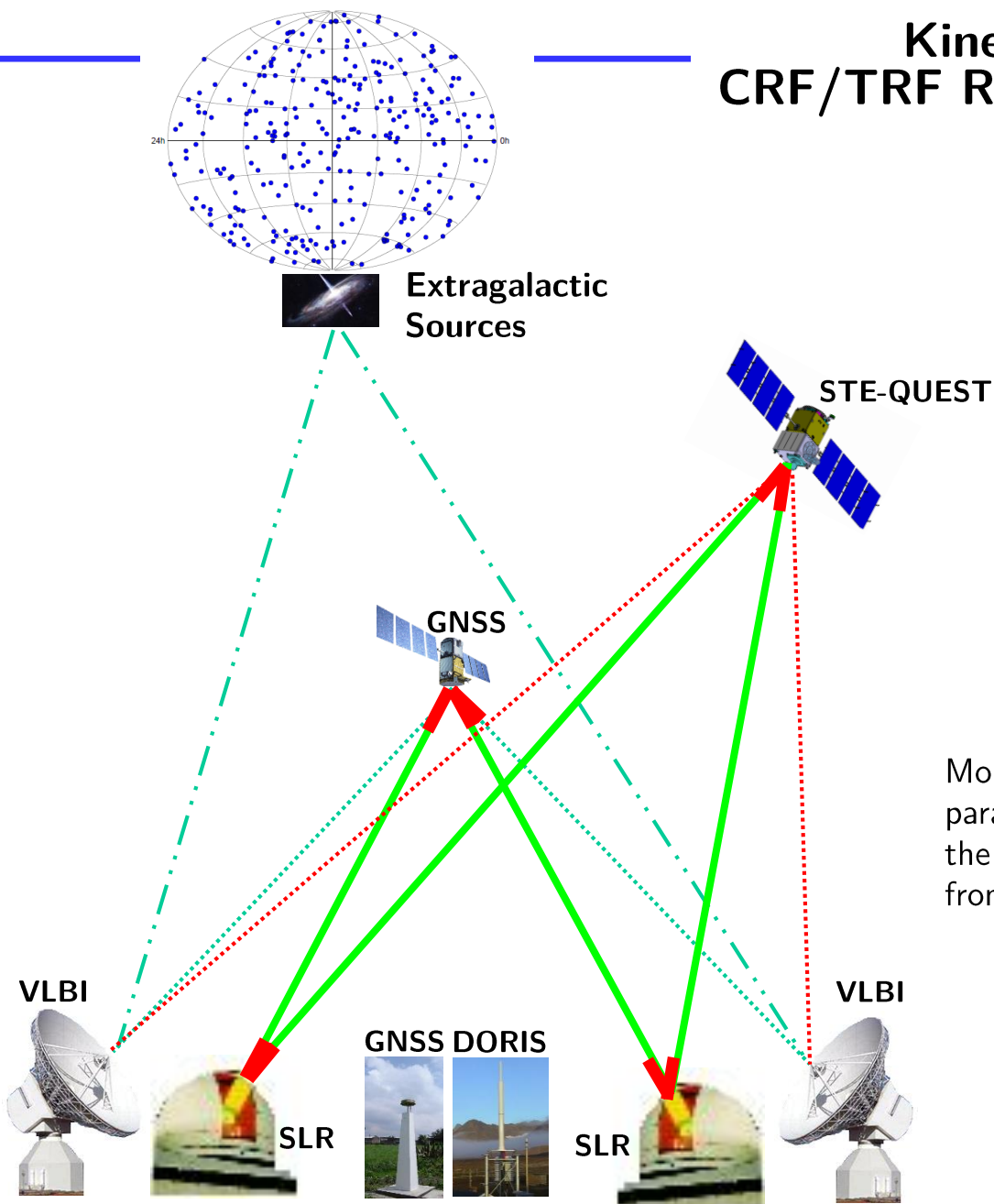
(Cheng, 2012)

Determination of the long-wavelength variability in the gravity field of Earth with STE-QUEST (central term and J<sub>2</sub>) that are either not observed or poorly observed by GRACE/GOCE (e.g. J<sub>2</sub>)

- **Highly elliptic orbit**

Long-term geoid change due to variability in J<sub>2</sub> is in the order of **~0.2 mm/y**

# Kinematic and Dynamic CRF/TRF Realization with STE-QUEST



**Double-Difference Approach**  
**GNSS, SLR, VLBI, DORIS**

**– BIAS FREE –**

**+**

**Optical/Microwave Metrology  
Link**

**+**

**STE-QUEST Clock**

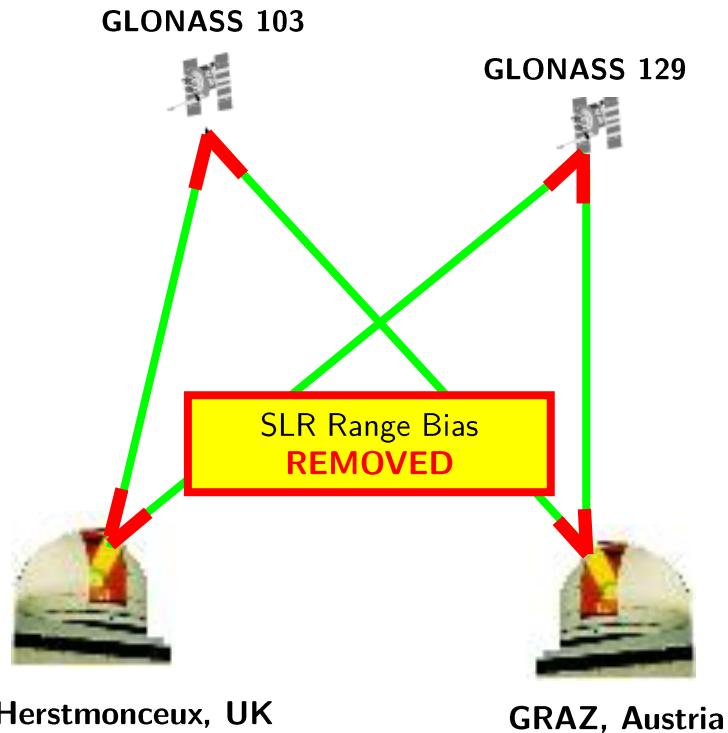
**Integrated TRF+CRF+Earth Rotation**

Monitoring of the Earth rotation and orientation parameters making use of the highly elliptical orbit of the STE-QUEST mission (UT1) and VLBI tracking from the ground (quasars/GNSS satellites)

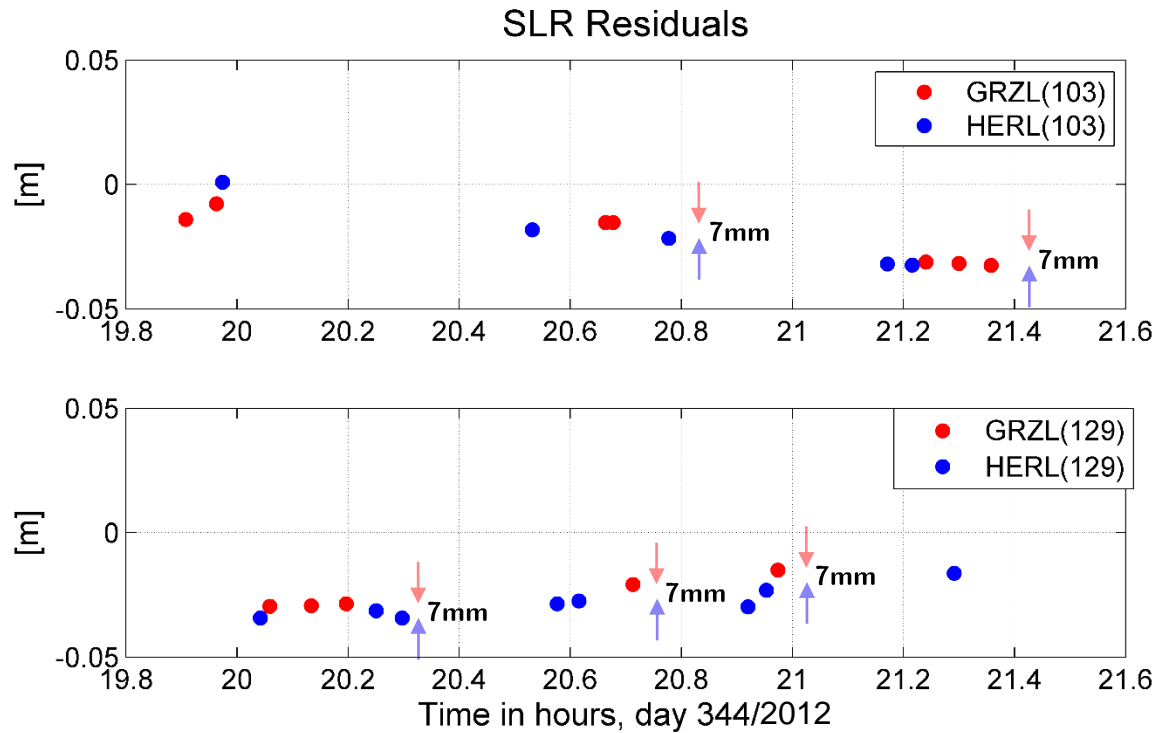
**Combination of data on  
observation level  
or normal-equation level**

# First SLR Double-Differences: The mm-SLR!

## SLR Double-Differences



Simultaneous SLR ranging to  
GLONASS 103&129 at mm-level!



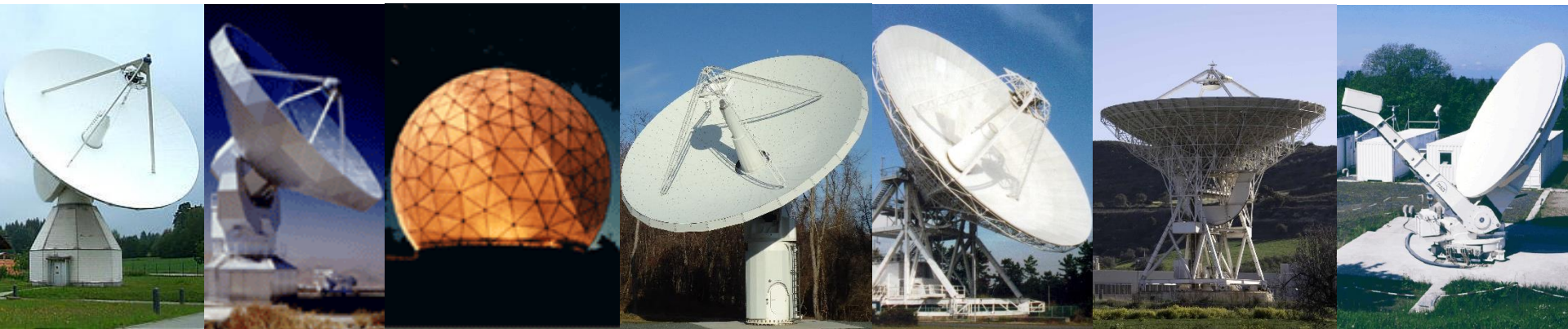
(Svehla et al., 2013)

Same double-difference approach could be  
applied to STE-QUEST with mm-accuracy!

# STE-QUEST and IVS - International VLBI Service of IAG

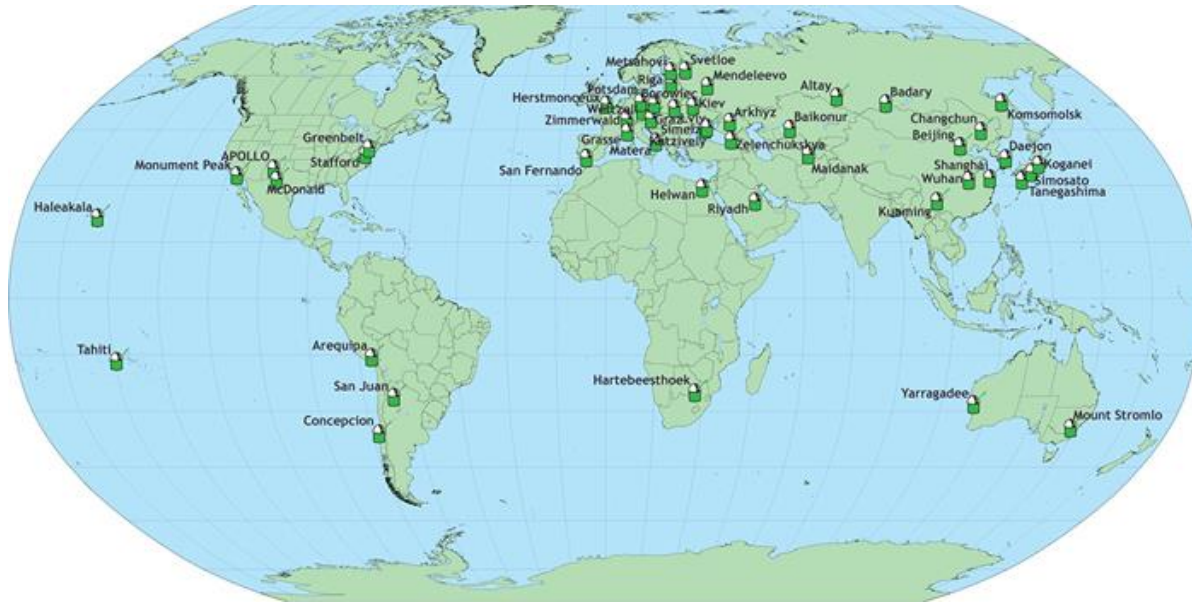


- ICRF2: S/X-Band 2.3/8.4 GHz
- VLBI2010 S/X-Band 2.3-14(18) GHz
- First Celestial frame at X/Ka-Band (8.4/32 GHz)
- VLBI is going towards higher radio-frequencies
- Dedicated phased-array antenna under development for Galileo and GPS reflectometry with beam forming on receive. Heritage from the Metop, Metop-SG.





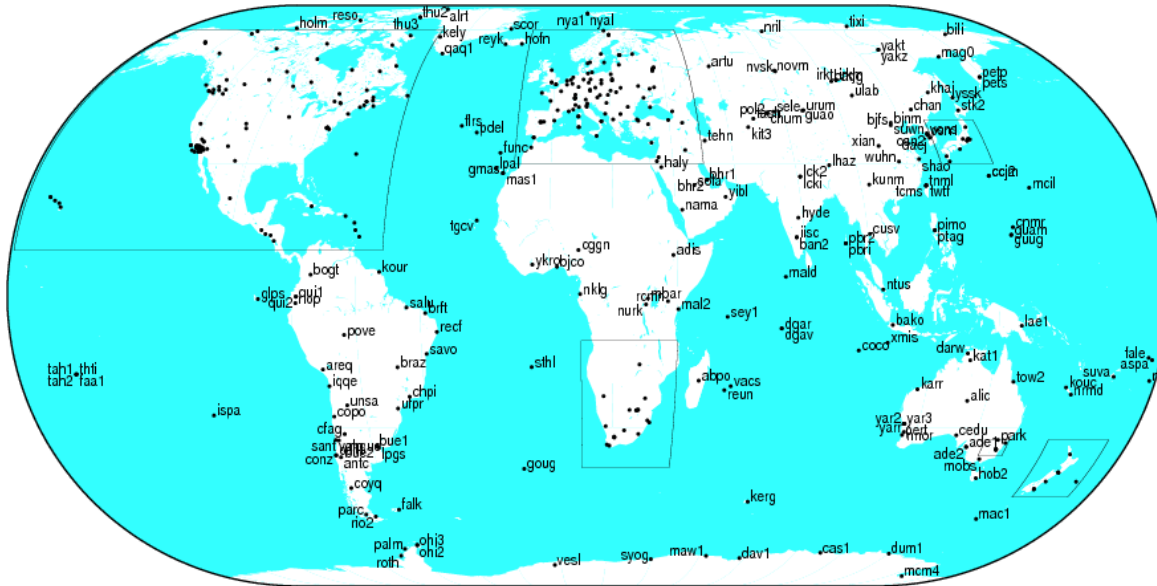
# STE-QUEST and ILRS - International Laser Ranging Service of IAG



- SLR retro-reflector with zero signature
- mm-SLR ranging in double-difference mode has been demonstrated
- limit of the SLR ranging precision/(accuracy) at about 0.1-0.2 mm for the best SLR stations



# STE-QUEST and IGS - International GNSS Service of IAG



- Combined GNSS/DORIS tracking on AGGA-4 chip (ESA)
- All-GNSS-type receiver AGGA-4 (ESA) with GPS, Galileo, GLONASS, Beidou
- GOCE, Swarm, Sentinel-3, Jason-CS, etc...

SM7 2013 May 17 16:45:31



# STE-QUEST and IDS - International DORIS Service of IAG



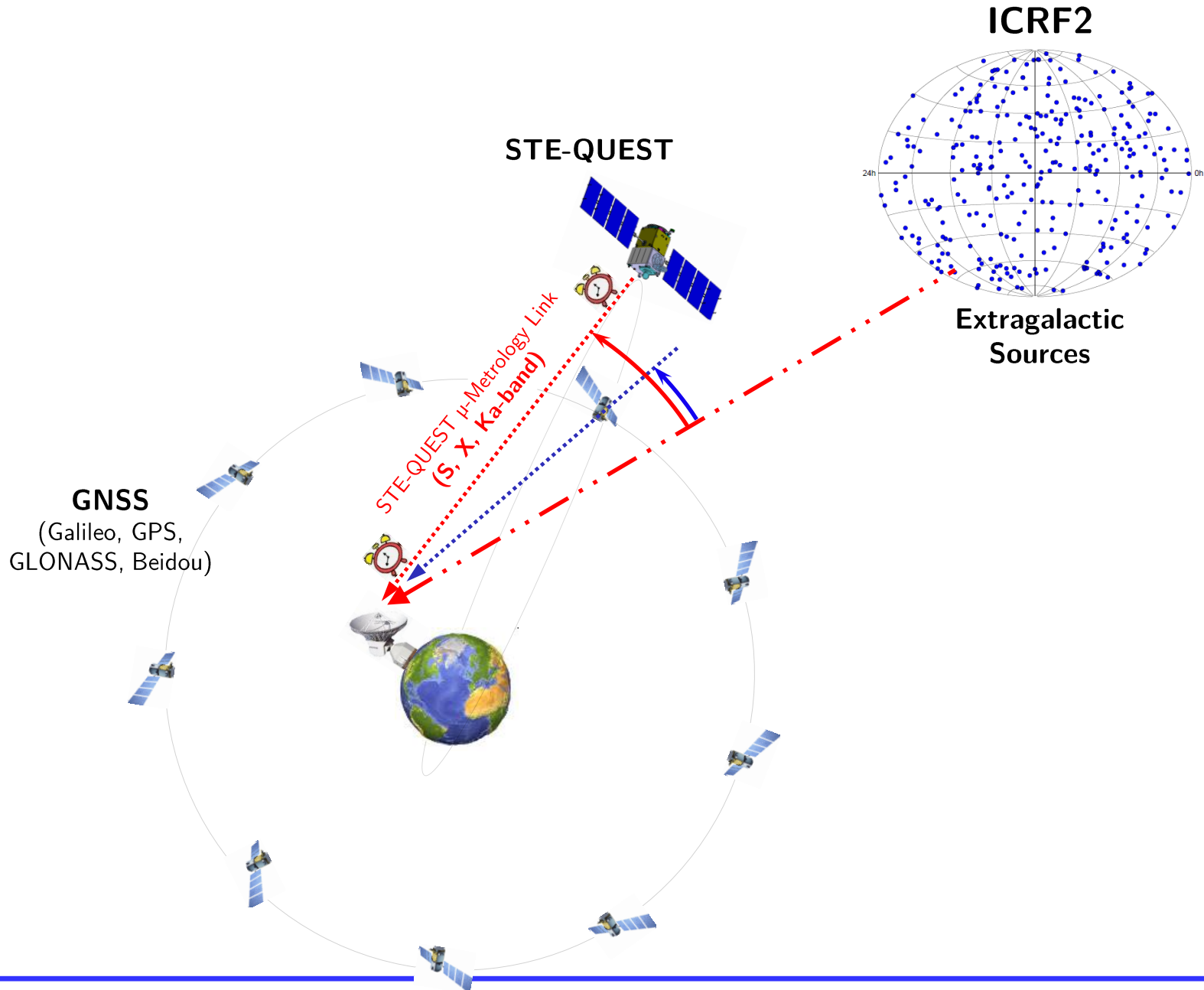
- GRASP Mission plans to use Trig GNSS receiver (second generation Blackjack GPS receiver) with DORIS tracking integrated.
- AGGA-4 chip (ESA) would need to be adapted for DORIS tracking (also for future altimetry missions).
- A dedicated flat phased-array antenna (nadir) for both GNSS and DORIS at higher altitudes.

400 MHz / 2 GHz    2 GHz phase centre  
(actual DORIS measurements)

Reference point



# Ground VLBI with STE-QUEST



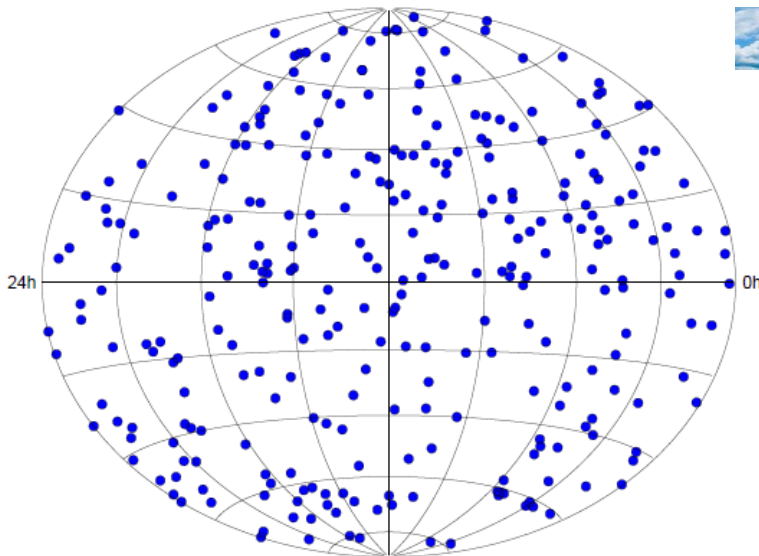
# Space VLBI with STE-QUEST Clock

From S/X towards X/Ka/(W)-band

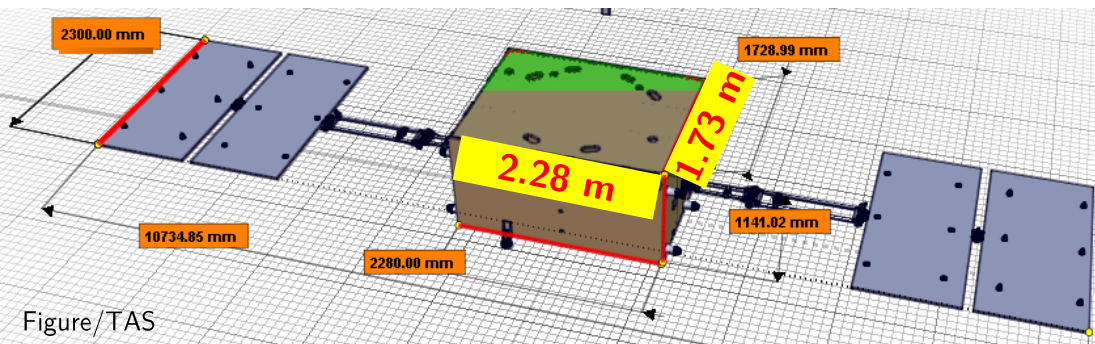
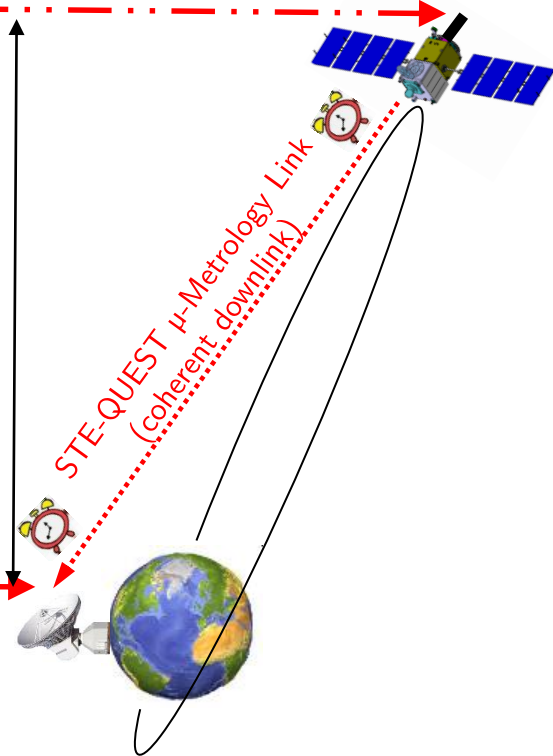
Advanced Phased-Array Antenna Design with beam forming on receive + STE-QUEST Clock (top side) VLBI/(GNSS)

Extragalactic Sources

No Clouds



~ 60 000 km

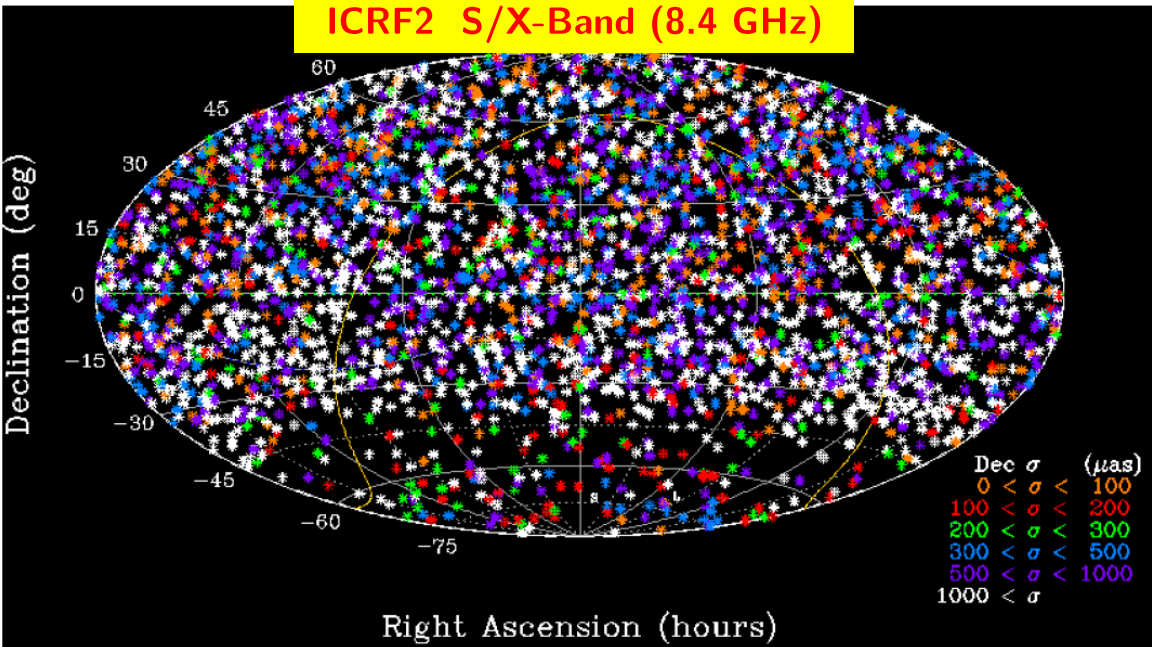


- Phased-array antenna with beam forming on receive VLBI/(GNSS)
- Making use of the high-performing STE-QUEST attitude system (GAIA AOCS)

Figure/TAS

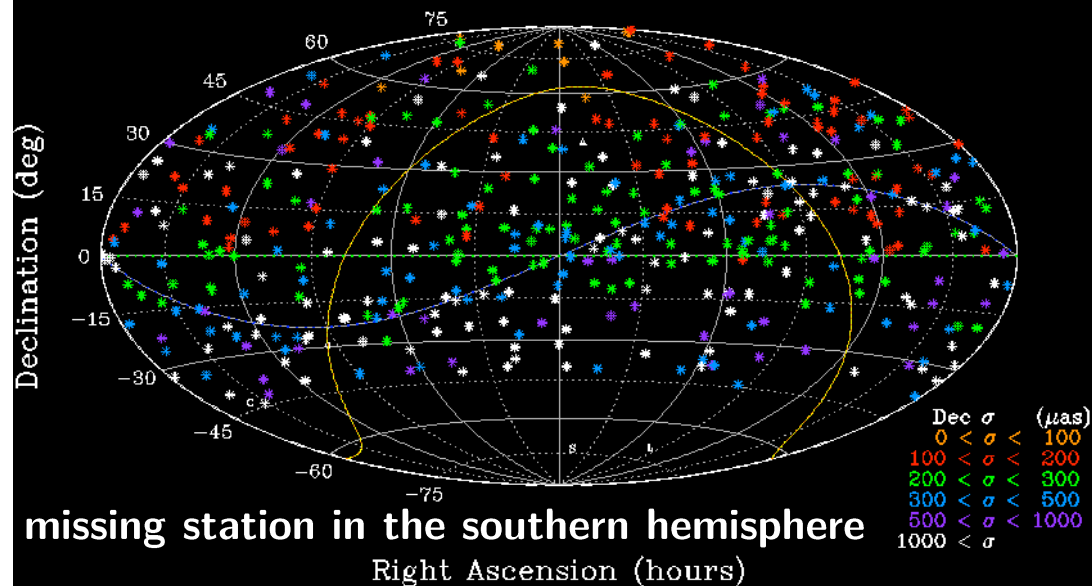
# Towards ICRF at X/Ka-Band (32 GHz)

## ICRF2 S/X-Band (8.4 GHz)



## ICRF at X/Ka-Band (32 GHz) 469 Sources

Distribution of 436 Sources



## ICRF2 S/X-Band

- # defining sources: 295
- # total sources: 3414 (3119 compact sources)
- Noise floor:  $\sim 40 \mu\text{as}$ , 5-6 $\times$  better than ICRF1
- Axis stability:  $\sim 10 \mu\text{as}$ , 2 $\times$  better than ICRF1 (IERS Conventions 2010)

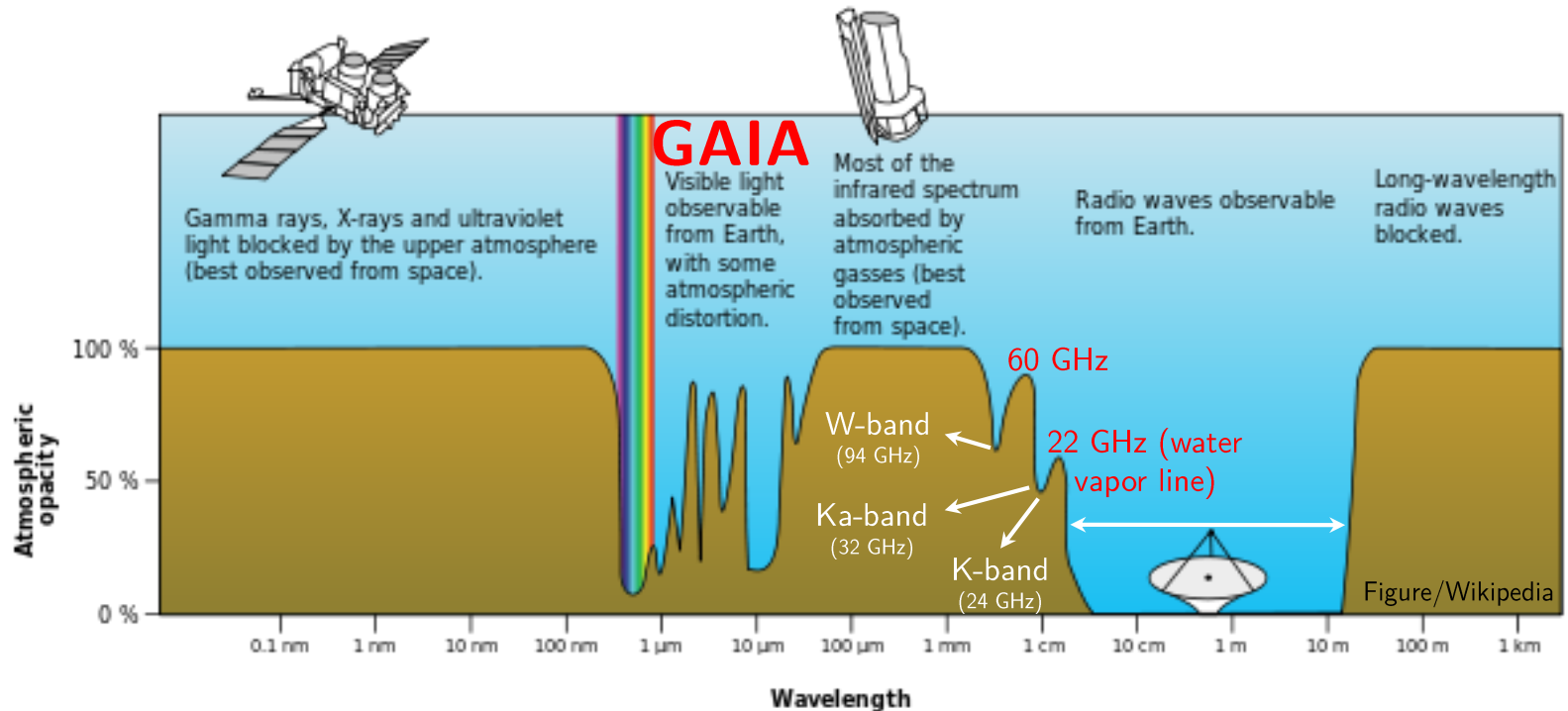
(used sampling rate 112 Mbps at X/Ka-Band)

(Jacobs, et al, 2010)

missing station in the southern hemisphere

Right Ascension (hours)

# Survey of Extragalactic Sources at S/X/Ka/(W)-band



**ICRF2:** International Celestial Reference Frame at S/X-band = **2.3/8.4 GHz**

**VLBI2010:** **2-14 GHz**, later 2-18 GHz

**K-band (VLBA):** **24 GHz**

**X/Ka-band:** **8.4/32 GHz** Radio-Science Experim., Mars Reconnaissance Orbiter, BepiColombo, JUICE, Netlander

**Ka/towards W-band** (driven by higher telemetry rates, radio-science experiments, space missions, iono-effects, etc.)

- Higher the R/F frequency smaller is the antenna
- Possible optical data modulation – larger sampling rate (1 - <10 Gbps) – **sensitivity**

# Towards ICRF at X/Ka-Band (32 GHz) and Higher (W-band)

## Advantages

- main driver are new space missions (Mars Reconnaissance Orbiter, BepiColombo, JUICE, Netlander...) requiring higher telemetry rates, radio-science, improved deep-space navigation (gravity field), lower iono/solar plasma-effects, etc.
- Higher telemetry data rates in deep space
- Onboard RF systems are smaller (antenna) and with lower weight
- Avoided RF Interference at S-band
- Ionosphere & solar plasma effects decreased by 16-100× at 32 GHz/90 GHz compared to 8 GHz
- Observation possible closer to Sun/Galactic center
- Very compact sources (spatial distribution of flux) that give more stability in positions over time!
- **Ka-positions closer to optical position (GAIA) compared to ICRF2 in S/X-band**

## Disadvantages

- More weather sensitive (close to 22 GHz water vapor line)
- Antenna pointing requirements 4-10× higher at 32 GHz/90 GHz compared to 8 GHz (beam forming technique)
- In order to increase sensitivity sampling rate needs to be 4-10× higher at 32 GHz/90 GHz compared to 8 GHz



# STE-QUEST Space VLBI as the link between GAIA Optical & Radio VLBI Frame

## ICRF2 S/X-Band

# defining sources: 295  
# total sources: 3414 (3119 compact sources)  
Noise floor:  $\sim 40 \mu\text{as}$   
Axis stability:  $\sim 10 \mu\text{as}$   
(IERS Conventions 2010)

## GAIA

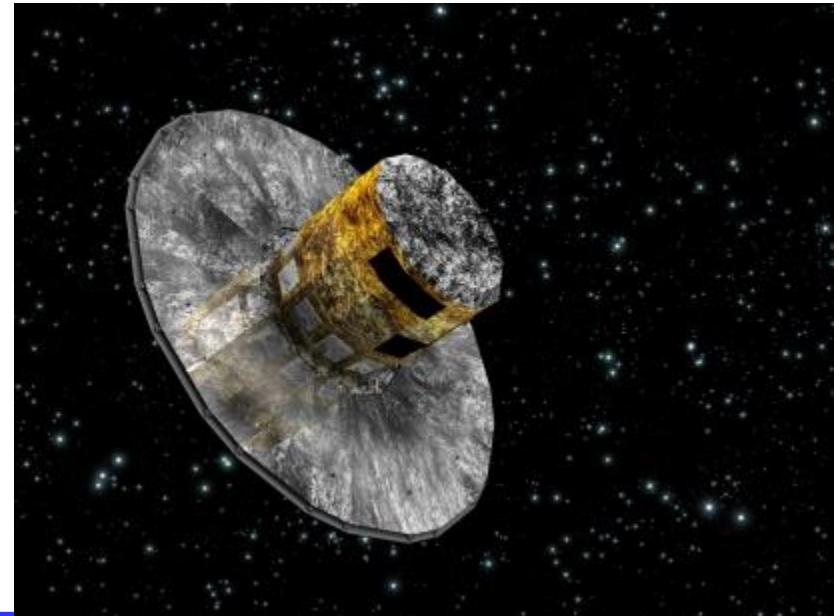
# optically bright quasars ( $V < 18 \text{ mag}$ )  $\sim 2000$

### Motivation: Ka-positions closer to optical position (GAIA) than ICRF2 in S/X-band

- The alignment of the Hipparcos Catalogue to the ICRF was realized with a standard error of **0.6 mas** for the orientation at epoch 1991.25 and **0.25 mas/yr** for the spin (Kovalevsky et al., 1997)
- The IAU recommendations stipulate that the direction of the Conventional Reference Pole should be consistent with that of the **FK5**. (IERS Conventions 2010)

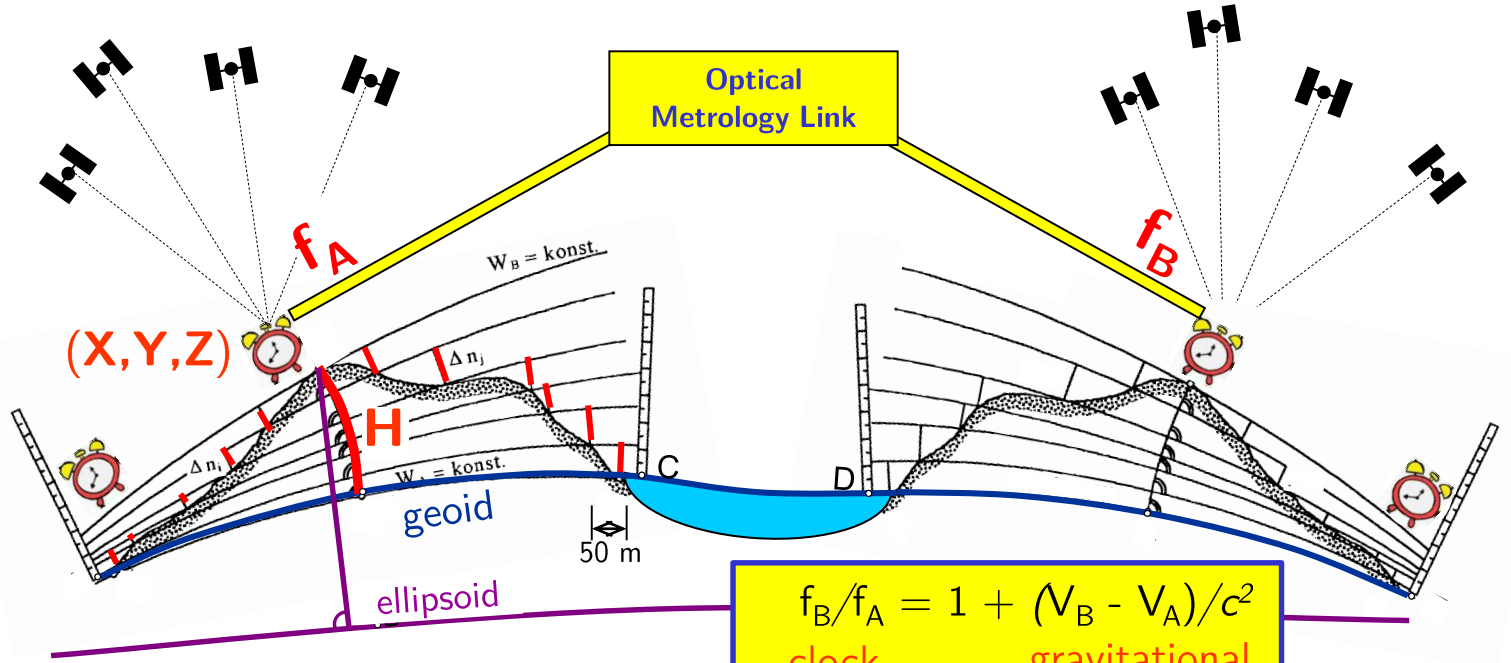
Out of 469 sources of the current Ka-band Celestial Frame:

- **132 objects are optically bright ( $V < 18 \text{ mag}$ )** (Garcia-Miro et al, 2012)
- for 71 there is no data
- are without data from a station in the southern hemisphere
- **5-15  $\mu\text{as}$**  potential precision for 3D frame tie with GAIA (Garcia-Miro et al, 2012)



# STE-QUEST: High-accuracy Relativistic Geodesy

GNSS  
(GPS, Galileo, ...)



$$f_B/f_A = 1 + (V_B - V_A)/c^2$$

clock frequency      gravitational potential

**Geometry from GPS (X,Y,Z) + Dynamic Heights (H) from optical clocks**

## Optical Metrology Link

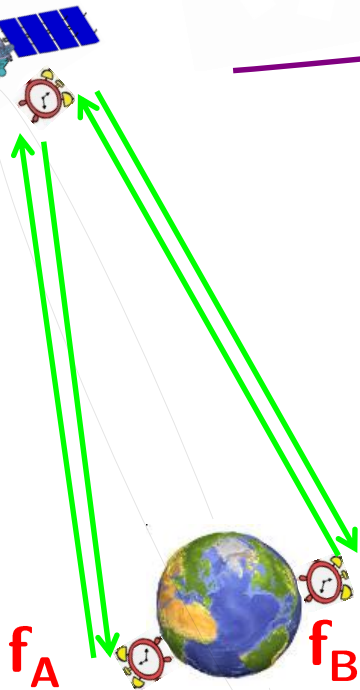
- Atmospheric turbulences (there is a solution!)
- Long light-travel time (there is a solution!)

## Microwave Metrology Link

- Higher-order ionosphere terms (there is a solution!)
- Atmospheric turbulences, multipath (there is a solution!)
- Long light-travel time (there is a solution!)

**Metrology Link with**  
**<10<sup>-18</sup> accuracy**  
**is FEASIBLE!!!**

- there is a solution for the metrology link after several years of looking at this problem...



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**Many Thanks**